

Project Planning Under Temporal Uncertainty

S. Biundo • R. Holzer • B. Schattenberg

University of Ulm



Project Planning

- **Project schedule vital for SW developers**
 - Calculate costs, meet project deadlines
- **Support by present-day PM tools?**
 - Highlighting off-schedule project threads
 - “Please provide adequate buffer times”
- **AI planning offers effective support during project definition**
 - Adequate formalism for capturing procedures and supporting abstract action specification
 - Reasoning about uncertainty



HTN Formalism

○ STRIPS-like operator instances as primitive tasks

$$o = (\text{prec}(o), \text{add}(o), \text{del}(o))$$

○ Abstract actions represented by complex tasks

$$d = (T, \prec, V)$$

$$m = (t, (T_t, \prec_t, V_t))$$

○ Methods implement complex tasks by task networks

$$T' = (T \setminus t) \cup T_t$$

$$\prec' = (\prec \setminus \prec_\delta) \cup \prec_t \cup$$

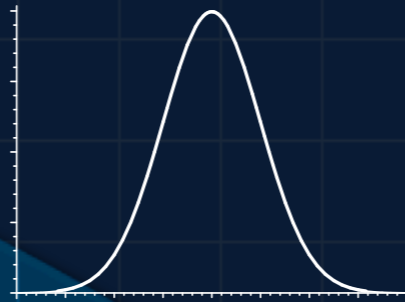
$$\{(t_a, t_t) \mid (t_a, t) \in \prec, t_t \in T_t\} \cup$$

$$\{(t_t, t_a) \mid (t, t_a) \in \prec, t_t \in T_t\}$$

$$V' = V \cup V_t$$

Stochastics

$$rv(o) = \mathcal{X}_{\mathcal{N}(\mu, \sigma^2)}$$



$$D_{\mathcal{X}_{D_1}^1 + \mathcal{X}_{D_2}^2}(t)$$

$$:= \int_{-\infty}^{+\infty} D_1(\tau) D_2(t - \tau) d\tau$$

$$\mathcal{X}^i \sim \mathcal{N}(\mu_i, \sigma_i^2) :$$

$$\sum_i \mathcal{X}^i \sim \mathcal{N}\left(\sum_i \mu_i, \sum_i \sigma_i^2\right)$$

○ **Continuous random variable**

○ **Duration of operator**

○ **Convolution for operator sequences**

○ **Normal distribution**

○ **Convolution computation**

○ **Can approximate most stochastic processes**

Stochastics

$$\Pr[\mathcal{I} + \mathcal{Y}^i \geq 0]$$

convoluted path duration

initial time bound

$$\Pr[\mathcal{X}_{\mathcal{N}(\mu, \sigma^2)} < a]$$
$$:= \int_{-\infty}^a \mathcal{N}(\mu, \sigma^2) dx$$
$$= \int_{-\infty}^a \frac{1}{\sqrt{2\sigma^2\pi}} e^{-\frac{(x-\mu)^2}{\sigma^2}} dx$$

- Probability of success
 - Convolute path operators
 - Approximate anti-derivate
- Critical Path: minimal probability of success



Propagating Durations

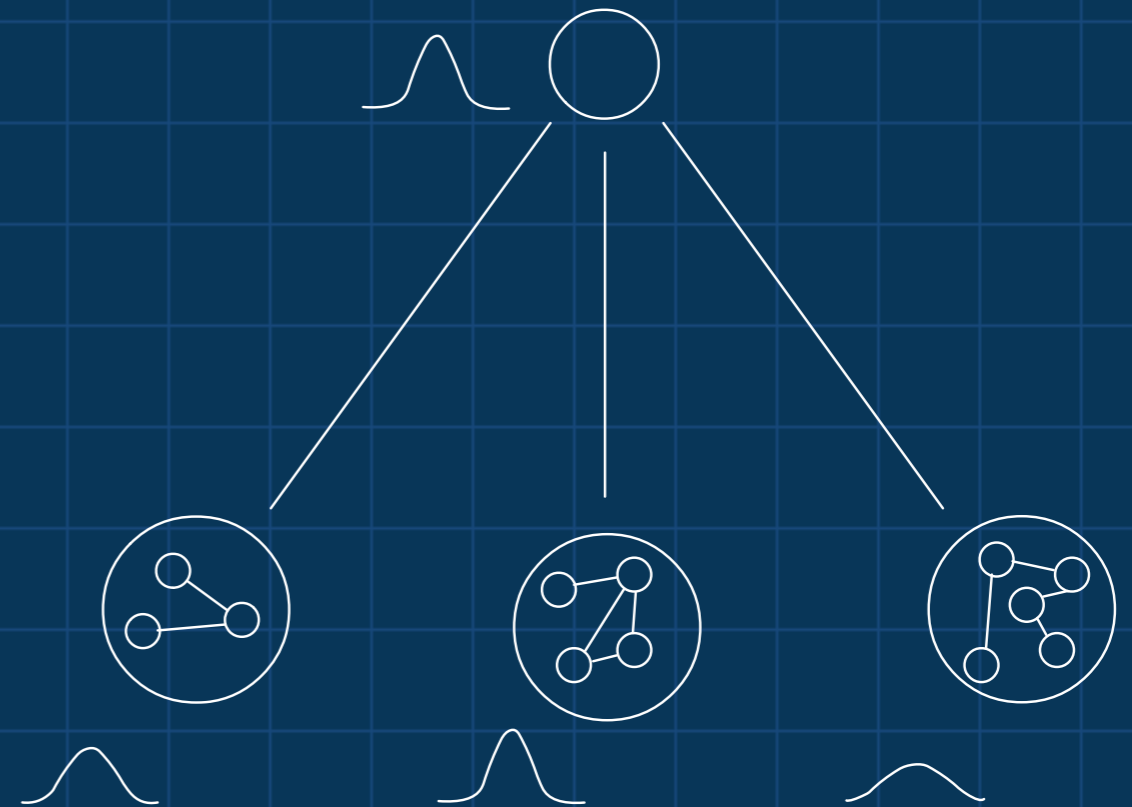
○ Preprocessing Phase

○ Compute underestimating distributions for paths in primitive task networks

○ Propagate into abstract tasks

○ Compute distributions for processed networks, etc.

○ Heuristic for Task Expansion

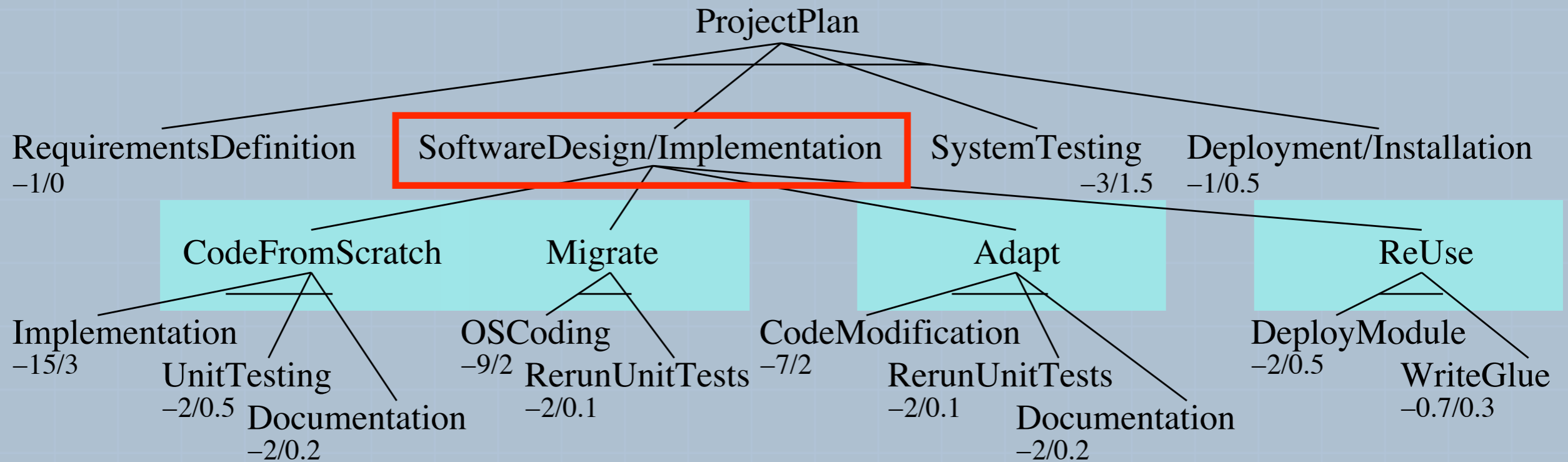


$$\min \left(\mathcal{X}_{\mathcal{N}(\mu_i, \sigma_i^2)} \right) \\ := \mathcal{Y}_{\mathcal{N}\left(-\min_i(|\mu_i|), \min_i(\sigma_i^2)\right)}$$

Example

-2.7/0.8

Underestimation for SD/I



-19/3.7

-11/2.1

-11/2.3

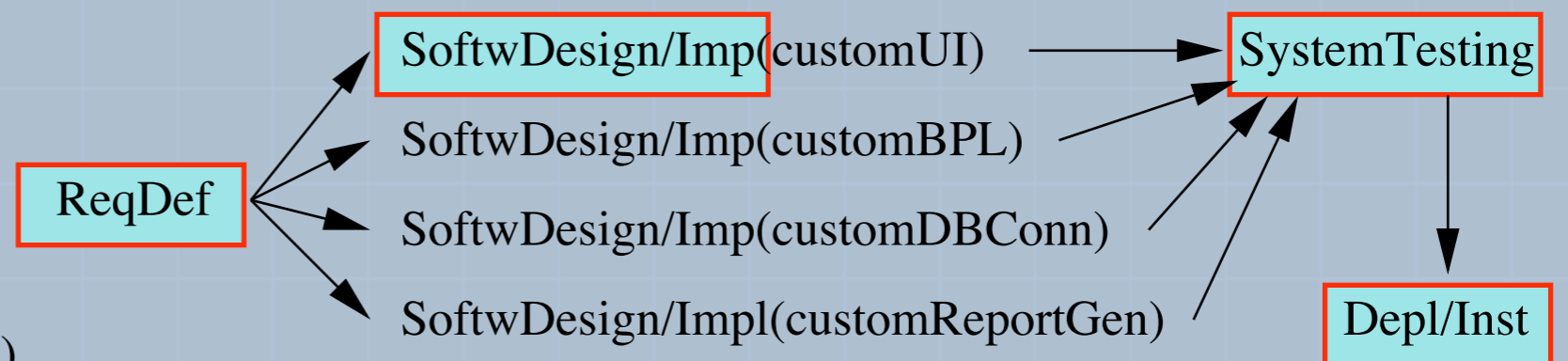
-2.7/0.8

Propagated duration

Example

Project deadline is 36 days, acceptable prob. of success is 85%

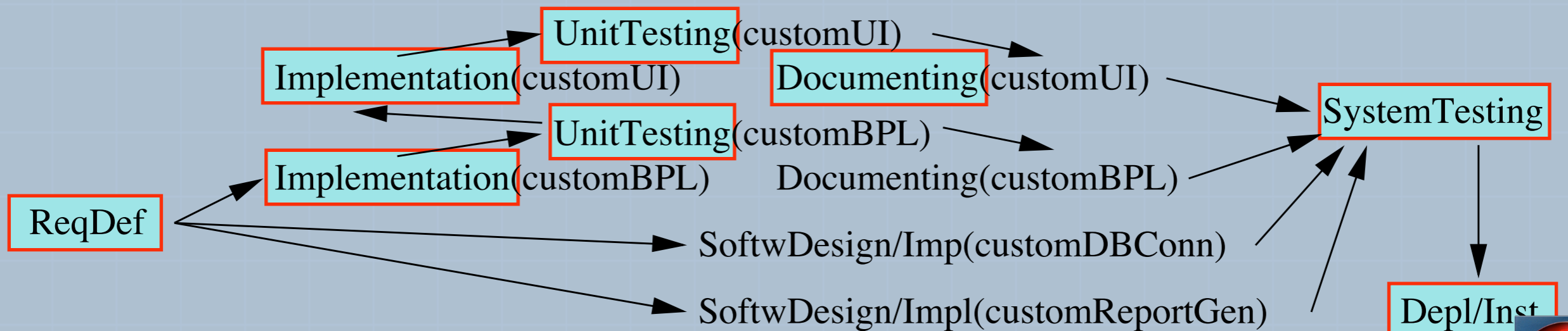
in-Repository(RepGen-16004)
OS(customUI, Linux)
OS(customBPL, Linux)
OS(UI-2705, Win)
OS(DBC-Orcl-5, Sol)
matches(func-req-A, DBC-Orcl-5)
interfaces(customUI, customBPL) . . .



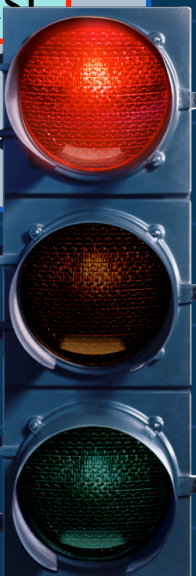
$$Pr[\mathcal{Z}_{\mathcal{N}(28.3, 2.8)} \geq 0] = Pr[\mathcal{I}_{\mathcal{N}(36, 0)} + \mathcal{Y}_{\mathcal{N}(-7.7, 2.8)}^1 \geq 0] \approx 100\%$$



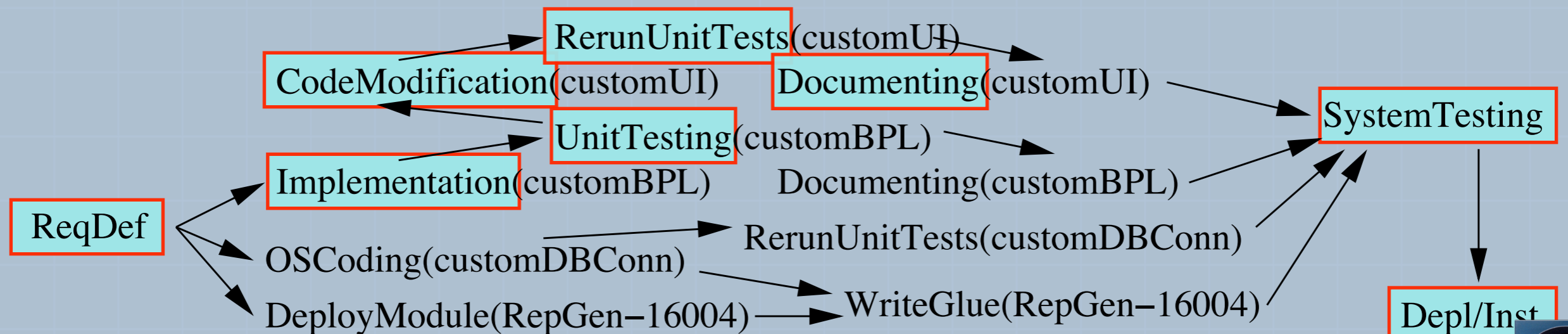
Example



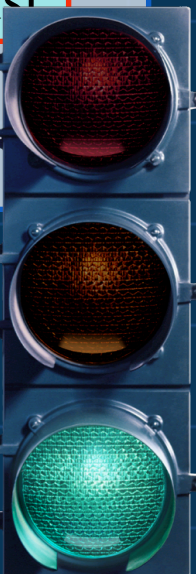
$$Pr[\mathcal{Z}_{\mathcal{N}(-5,9.2)} \geq 0] = Pr[\mathcal{I}_{\mathcal{N}(36,0)} + \mathcal{Y}_{\mathcal{N}(-41,9.2)}^1 \geq 0] \approx 4.96\%$$



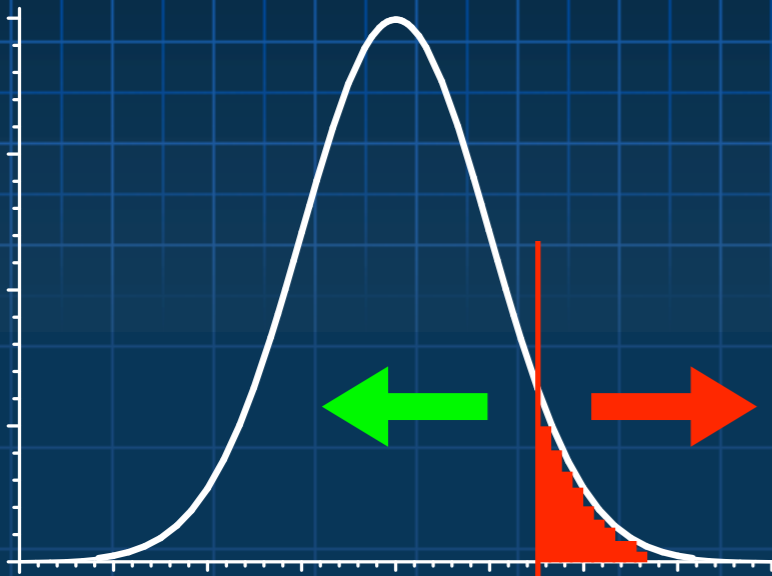
Example



$$Pr[\mathcal{Z}_{\mathcal{N}(7,7.8)} \geq 0] = Pr[\mathcal{I}_{\mathcal{N}(36,0)} + \mathcal{Y}_{\mathcal{N}(-29,7.8)}^1 \geq 0] \approx 85.86\%$$



Conclusion



- HTN Planning with probabilistic action durations and resource consumption for **risky** scenarios
- Propagation of distribution underestimations for cutting futile expansions
- Implemented in a multi-agent based planning framework