

Wiener sausage and sensor networks

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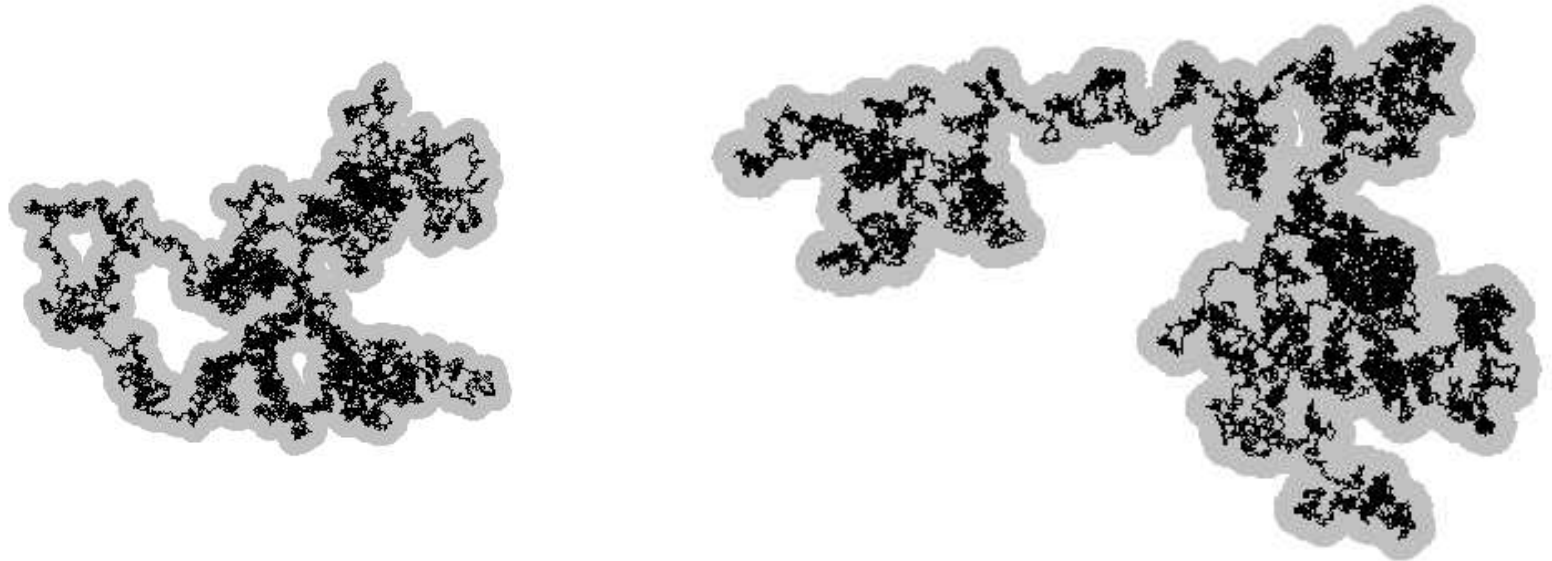
Joint research with R. Černý, D. Meschenmoser, S. Funken, J. Rataj and
V. Schmidt

Overview

- Sensor networks
- Wiener sausage
 - Mean volume and surface area
 - Almost sure approximation and convergence of curvature measures
- Boolean model of Wiener sausages
 - Capacity functional and volume fraction
 - Contact distribution function and covariance function
 - Specific surface area
- Outlook

Motivation: sensor networks

- Finding an object in a medium using a totally random strategy (G. Kesidis et al. (2003), S. Shakkottai (2004)): a set of sensors with reach $r > 0$ move randomly in the medium. Target detection area of a sensor = Wiener sausage S_r



Paths of two sensors with reach $r = 20$ and their target detection areas

Motivation: sensor networks

- **Sensor network**: Sensors are located “at random” in space moving according to the Brownian motion.
- **Target detection area** of such network: the **Boolean model** of Wiener sausages
- **Target detection probability**: $p = 1 - e^{-\lambda \mathbb{E} |S_r|}$, where λ is the intensity of the Poisson process of initial positions of sensors and $\mathbb{E} |S_r|$ is the mean volume of the Wiener sausage
- **Other specific intrinsic volumes**? \implies find other mean intrinsic volumes of S_r
- E.g., the **mean surface area** $\mathbb{E} \mathcal{H}^{d-1}(\partial S_r)$

Polyconvex sets and sets of positive reach

● **Polyconvex sets:** $K = \cup_{i=1}^n K_i$, where K_i are convex bodies.

● **Sets of positive reach:** For a closed subset $A \subseteq \mathbb{R}^d$, define

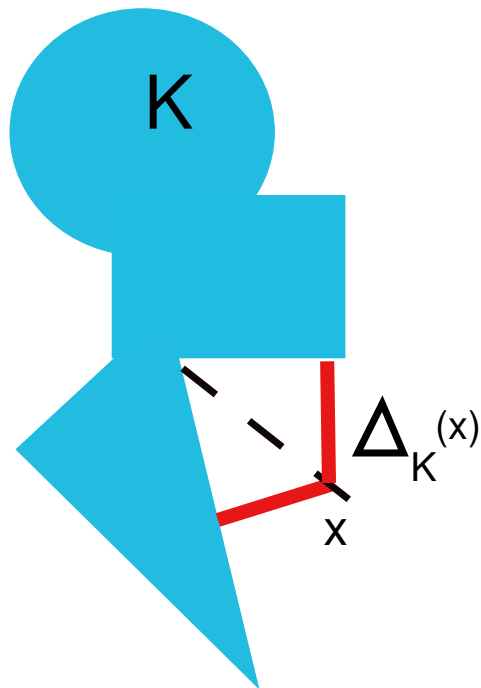
$$\text{reach } A = \sup\{r \geq 0 : \forall x \in \mathbb{R}^d, \Delta_A(x) < r \implies \text{card } \Sigma_A(x) = 1\},$$

where $\Delta_A(x)$ is the **distance** from $x \in \mathbb{R}^d$ to A and

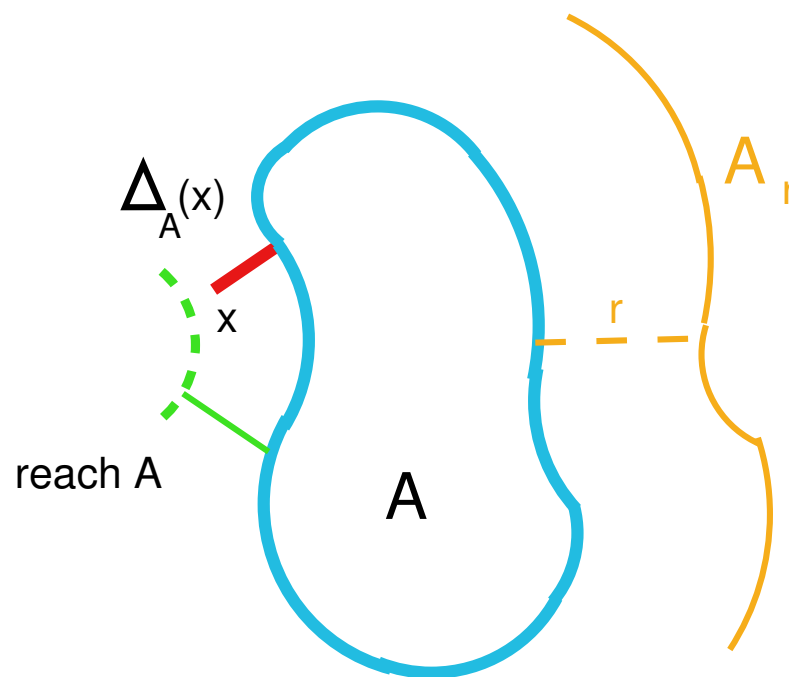
$$\Sigma_A(x) = \{a \in A : |x - a| = \Delta_A(x)\}$$

is the set of all metric projections of x on A . A is said to be of **positive reach** if $\text{reach } A > 0$.

Polyconvex sets and sets of positive reach



A polyconvex set



A set of positive reach

The **parallel set** of A , $r > 0$:

$$A_r = A \oplus B_r(o) = \{x \in \mathbb{R}^d : \Delta_A(x) \leq r\}$$

Intrinsic volumes

- Steiner's formula (H. Federer (1959)): If A is a set of positive reach then

$$|A_r| = \sum_{i=0}^d \omega_i r^i V_{d-i}(A), \quad 0 \leq r < \text{reach } A,$$

where

- $V_d(\cdot) = |\cdot|$ is the Lebesgue measure in \mathbb{R}^d (**volume**),
- ω_i is the volume of the unit i -ball
- V_i is the i -th **intrinsic volume** of A , $i = 0, \dots, d$. In particular, V_0 is the **Euler-Poincaré characteristic** and V_{d-1} is one half of the **surface area**.

Curvature measures

- Local version of Steiner's formula: For any Borel subset $F \subset \mathbb{R}^d$

$$|(A_r \setminus A) \cap \xi_A^{-1}(F)| = \sum_{i=1}^d \omega_i r^i C_{d-i}(A; F), \quad 0 \leq r < \text{reach } A,$$

where

- $\xi_A(x)$ is the nearest point of A to x
- the signed Radon measure $C_i(A; \cdot)$ concentrated on ∂A is the i th curvature measure of A , $0 \leq i \leq d - 1$
- If ∂A is compact then $C_i(A; \mathbb{R}^d) = V_i(A)$, $i = 0, \dots, d - 1$.

Brownian motion

- **Wiener process** $\{W(t) : t \geq 0\}$: a random process with continuous paths defined on $(\Omega, \mathfrak{F}, P)$ such that
 - $W(0) = x \in \mathbb{R}$ a.s.,
 - W has independent increments,
 - $W(t) - W(s) \sim N(0, \sigma^2(t - s)), 0 \leq s < t$.
- **Brownian motion** in \mathbb{R}^d initiated at $x = (x_1, \dots, x_d)$:

$$X(t) = (W_1(t), \dots, W_d(t)), \quad t \geq 0,$$

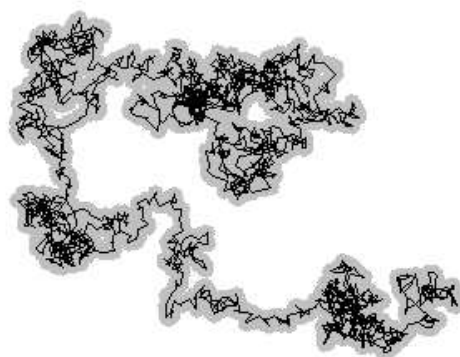
where W_1, \dots, W_d are independent Wiener processes starting at $x_1, \dots, x_d \in \mathbb{R}$.

Wiener sausage

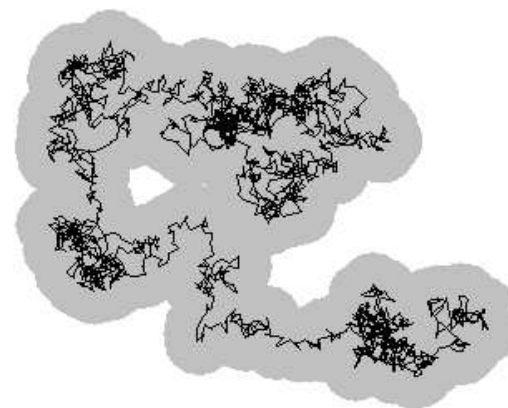
Let $S(T) = \{X(t) : t \in [0, T]\}$ be the path of X up to time $T > 0$.

- **Wiener sausage** S_r of radius $r > 0$:

$$S_r = S(T) \oplus B_r(o) = \{x \in \mathbb{R}^d : \Delta_{S(T)}(x) \leq r\}.$$



$r = 10$



$r = 40$

A realization of S_r

Intrinsic volumes of the Wiener sausage

- **Intrinsic volumes** $V_0(S_r), \dots, V_d(S_r)$ are well-defined a.s. for $d \leq 3, r > 0$;
 - $V_d(S_r) = V_S(r)$
 - $2V_{d-1}(S_r) = \mathcal{H}^{d-1}(\partial S_r)$
 - $V_i(S_r) = (-1)^{d-i-1} V_i(\overline{\mathbb{R}^d \setminus S_r})$, $i = 0, \dots, d-2$, where ∂S_r is a Lipschitz manifold with $\text{reach}(\overline{\mathbb{R}^d \setminus S_r}) > 0$ a.s.
- **Compute** $\mathbb{E} V_i(S_r)$, $i = 0, \dots, d$.

It is proved that $\mathbb{E} V_i(S_r) < \infty$, $i = d, d-1$ for all $d \geq 2$ and $\mathbb{E} V_0(S_r) < \infty$ for $d = 2$ (RSS 09, RSM 09).

Mean volume of the Wiener sausage

• Explicit formulae

- $d = 2$: A. Kolmogoroff and M. Leontowitsch (1933)
- $d = 3$: F. Spitzer (1964)
- $d \geq 4$: A. Berezhkovskii *et al.* (1989)

• Asymptotics of the volume

- R. Gettoor (1965)
- M. Donsker und S. Varadhan (1975)
- J.-F. Le Gall (1988): CLT for shrinking Wiener sausage
($T \rightarrow \infty$ or $r \rightarrow 0$)
- M. van den Berg and E. Bolthausen (1994)
- ...

Other mean curvature measures

- Mean surface area: RSS (2009)
- Support measures and mean curvature functions: G. Last (2006)
- Other mean intrinsic volumes $\mathbb{E} V_i(S_r)$, $i = 0, \dots, d - 2$: an open problem. Approximations can be obtained numerically (RSM (2009))

Mean volume of the Wiener sausage

A. Berezhkovskii, Yu. Makhnovskii, R. Suris (1989) : for $d \geq 2$

$$\mathbb{E} |S_r| = \omega_d r^d + \frac{d(d-2)}{2} \omega_d \sigma^2 r^{d-2} T + \frac{4d \omega_d r^d}{\pi^2} \int_0^\infty \frac{1 - e^{-\frac{\sigma^2 y^2 T}{2r^2}}}{y^3 (J_\nu^2(y) + Y_\nu^2(y))} dy,$$

where $J_\nu(y)$ and $Y_\nu(y)$ are Bessel functions of the first and second kind of order $\nu = (d-2)/2$ and $\omega_d = \pi^{d/2} / \Gamma(1 + d/2)$ is the volume of the unit d -ball.

Mean volume of the Wiener sausage

Bessel functions $J_\nu(y)$ and $Y_\nu(y)$ are linearly independent solutions of the Bessel diff. equation $y^2 f''(y) + yf'(y) + (y^2 - \nu^2)f(y) = 0$, and

$$J_\nu(y) = \sum_{k=0}^{\infty} \frac{(-1)^k (y/2)^{2k+\nu}}{k! \Gamma(\nu + k + 1)},$$

$$Y_\nu(y) = \frac{J_\nu(y) \cos(\nu\pi) - J_{-\nu}(y)}{\sin(\nu\pi)}.$$

In **three dimensions**, the above formula for the mean volume of S_r simplifies to

$$\mathbb{E} |S_r| = \frac{4}{3} \pi r^3 + 4\sigma r^2 \sqrt{2\pi T} + 2\pi \sigma^2 r T.$$

Mean surface area of the Wiener sausage

Theorem 1. Let S_r be the Wiener sausage in \mathbb{R}^d , $d \geq 2$. Then, it holds

$$\begin{aligned} \mathbb{E}\mathcal{H}^{d-1}(\partial S_r) &= d\omega_d r^{d-1} + \frac{4d^2 \omega_d r^{d-1}}{\pi^2} \int_0^\infty \frac{1 - e^{-\frac{\sigma^2 y^2 T}{2r^2}}}{y^3 (J_\nu^2(y) + Y_\nu^2(y))} dy \\ &+ d\omega_d \sigma^2 r^{d-3} T \left(\frac{(d-2)^2}{2} - \frac{4}{\pi^2} \int_0^\infty \frac{e^{-\frac{\sigma^2 y^2 T}{2r^2}}}{y (J_\nu^2(y) + Y_\nu^2(y))} dy \right) \end{aligned}$$

for *almost all radii* $r > 0$. For $d = 2, 3$, this formula holds for *all* $r > 0$. In the case $d = 3$, it simplifies to

$$\mathbb{E}\mathcal{H}^2(\partial S_r) = 4\pi r^2 + 8r\sigma\sqrt{2\pi T} + 2\pi\sigma^2 T.$$

Mean surface area of the Wiener sausage

Asymptotic behaviour (RSS 09)

$$\mathbb{E}\mathcal{H}^{d-1}(\partial S_r) \sim \begin{cases} \pi\sigma^2 T r^{-1} \log^{-2} r & \text{if } d = 2, \\ 2\pi\sigma^2 T & \text{if } d = 3, \\ d\omega_d\sigma^2 T \frac{(d-2)^2}{2} r^{d-3} & \text{if } d \geq 4 \end{cases} \text{ as } r \rightarrow 0.$$

Idea of the proof of Theorem 1

Theorem 2. For $d \leq 3$ and any $r > 0$, it holds

$$E \mathcal{H}^{d-1}(\partial S_r) = \frac{d E V_S(r)}{d r},$$

where $V_S(r) = |S_r|$. For dimensions $d \geq 4$, this relation holds for almost all $r > 0$.

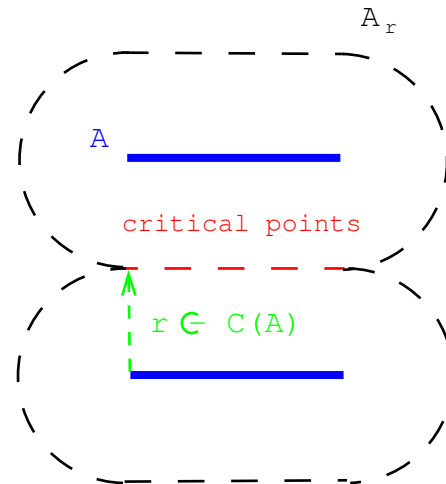
follows from the dominated convergence theorem and

Lemma 1. It holds

$$\mathcal{H}^{d-1}(\partial S_r) \stackrel{a.s.}{=} V'_S(r)$$

for all $r > 0$ if $d = 2, 3$ and almost all $r > 0$ if $d \geq 4$.

Idea of the proof of Theorem 1



The point $x \in \mathbb{R}^d$ is called **critical** for A if

$$x \in \text{conv}\{a \in A : |x - a| = d(A, x)\}.$$

The radius $r > 0$ is **critical** for A if \exists a critical point x for A with $d(A, x) = r$. Let $C(A)$ be the set of critical dilation radii r for A .

Idea of the proof of Theorem 1

Lemma 1 follows from

Theorem 3. Let $A \subset \mathbb{R}^d$ be any compact set. If $r \in (0, \infty) \setminus C(A)$ then $V'_A(r)$ exists and equals $\mathcal{H}^{d-1}(\partial A_r)$. Here $A_r = \{x \in \mathbb{R}^d : d(A, x) \leq r\}$ is the parallel neighborhood of A of radius $r > 0$ and $C(A)$ is the set of critical dilation radii for A .

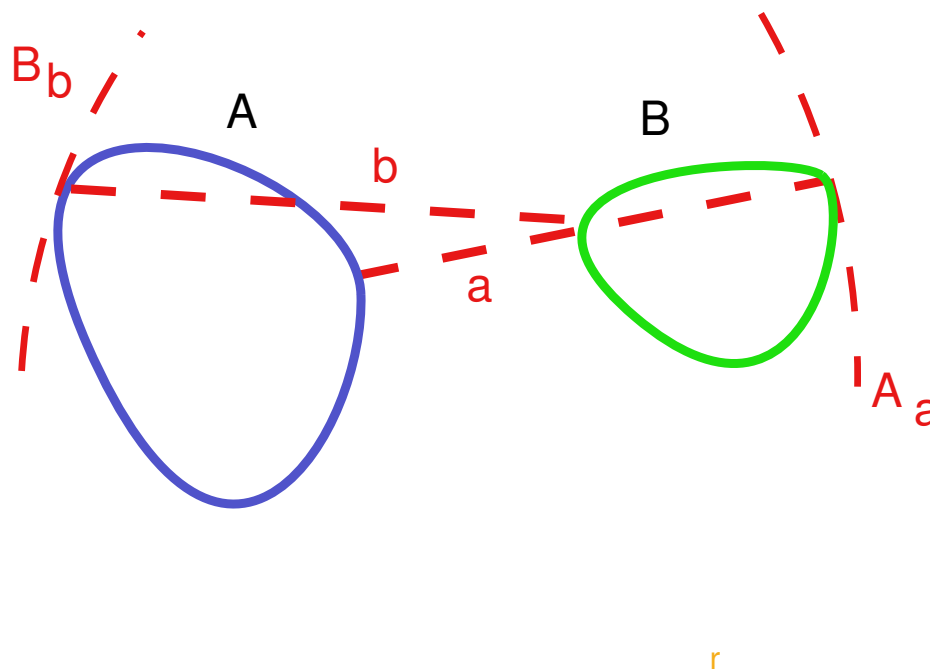
and

Theorem 4. Let $d \leq 3$. Then for any $r > 0$, $r \notin C(S(T))$ a. s. For $d \geq 4$, $r \notin C(S(T))$ a.s. for almost all radii $r > 0$. Here $S(T)$ is the path of the Brownian motion up to time instant $T > 0$.

Other mean intrinsic volumes

- **Compute** $\mathbb{E} V_i(S_r)$, $i = 0, \dots, d - 2$
- **Idea:** Approximate the Wiener sausage S_r a.s. by random polyconvex sets S_r^n with $\mathbb{E} V_i(S_r^n) \rightarrow \mathbb{E} V_i(S_r)$ as $n \rightarrow \infty$, $i = 0, \dots, d$
- **Method:** Use any a.s. piecewise linear approximation S^n of the Brownian path S w.r.t. the Hausdorff metric to approximate the Wiener sausage $S_r = S \oplus B_r(o)$ by $S_r^n = S^n \oplus B_r(o)$, e.g. the **Haar-Schauder approximation**
- **Goal:** Obtain $\mathbb{E} V_i(S_r)$ by computing $\mathbb{E} V_i(S_r^n)$ and using $\mathbb{E} V_i(S_r^n) \rightarrow \mathbb{E} V_i(S_r)$, $n \rightarrow \infty$, $i = 0, \dots, d - 2$

Approximation of the Wiener sausage



Hausdorff metric: For two nonempty compacts $A, B \subset \mathbb{R}^d$

$$d_H(A, B) = \min \{a > 0 : A \subseteq B \oplus B_a(o), B \subseteq A \oplus B_a(o)\}.$$

Convergence of curvature measures

Theorem 5.

If $d_H(S^n, S) \rightarrow 0$ as $n \rightarrow \infty$ almost surely, then it holds

- (i) $V_{S^n}(r) \rightarrow V_S(r)$ as $n \rightarrow \infty$ almost surely for **any** $r > 0$;
- (ii) $\mathcal{H}^{d-1}(\partial S_r^n) \rightarrow \mathcal{H}^{d-1}(\partial S_r)$ as $n \rightarrow \infty$ almost surely for **any** $r > 0$ if $d \leq 3$ and for **almost all** $r > 0$ if $d \geq 4$;
- (iii) $C_i(S_r^n; \cdot) \rightarrow C_i(S_r; \cdot)$ weakly as $n \rightarrow \infty$ almost surely for **any** $r > 0$ and $i = 0, \dots, d - 1$ if $d \leq 3$.

Convergence of curvature measures

Corollary 1. *It holds*

- (i) $\mathbb{E} V_{S^n}(r) \rightarrow \mathbb{E} V_S(r)$ as $n \rightarrow \infty$ for *any* $r > 0$;
- (ii) $\mathbb{E} \mathcal{H}^{d-1}(\partial S_r^n) \rightarrow \mathbb{E} \mathcal{H}^{d-1}(\partial S_r)$ as $n \rightarrow \infty$ for *any* $r > 0$ if $d \leq 3$ and for *almost all* $r > 0$ if $d \geq 4$.

Conjecture: $\mathbb{E} V_i(S_r^n) \rightarrow \mathbb{E} V_i(S_r)$ as $n \rightarrow \infty$ for $i = 0, \dots, d - 2$ if $d \leq 3$.

Open problem: Find a uniform integrable upper bound for $V_i(S_r^n)$, $V_i(S_r)$, $n \in \mathbb{N}$, $i = 0, \dots, d - 2$

Approximation of the Wiener sausage

Example

- For simplicity, consider $T = 1$.
- Set time instants $t_i = i/k_n$, $i = 1, \dots, k_n$ for $k_n \rightarrow \infty$, $n \rightarrow \infty$.
- **Vertices:** $X^n(t_i) = X(t_i)$, $i = 1, \dots, k_n$
- The path $S^n = \{X^n(t) : 0 \leq t \leq 1\}$ is a **piecewise linear curve** with $2^n + 1$ nodes lying on $S = \{X(t) : 0 \leq t \leq 1\}$.
- Set $S_r^n = S^n \oplus B_r(o)$, $n \in \mathbb{N}$.

Theorem 6. *It holds $d_H(S^n, S) \leq \max_{t \in [0,1]} |X^n(t) - X(t)| \rightarrow 0$ as $n \rightarrow \infty$ a.s.*

Approximation of the Wiener sausage

Special case: Haar-Schauder approximation

For the standard Brownian motion W ($\sigma^2 = T = 1$) holds

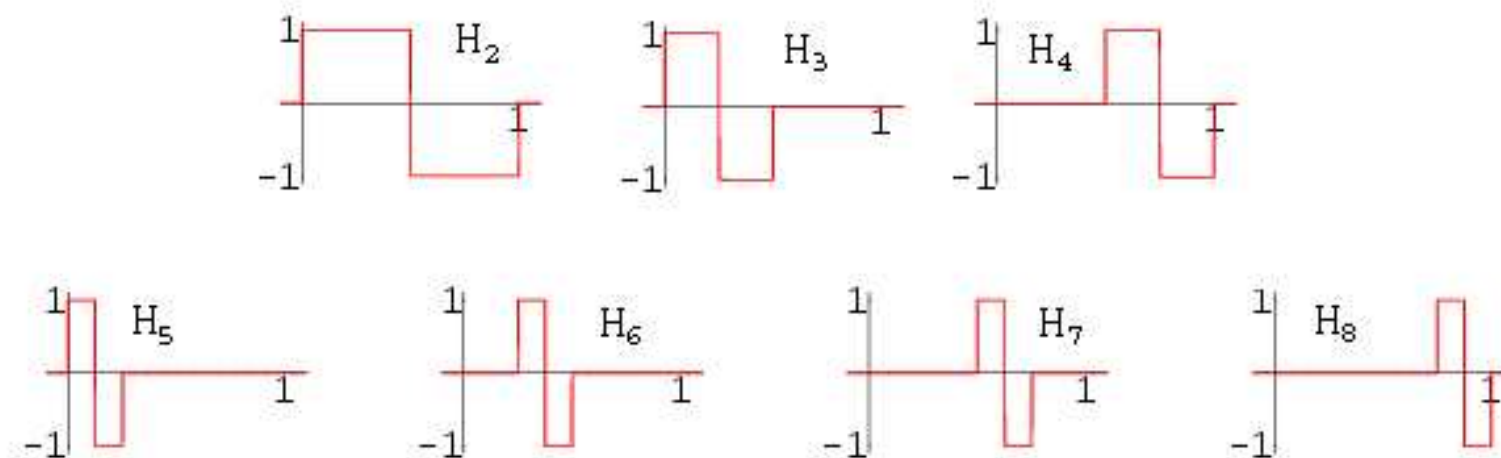
$$W(t) = \sum_{k=1}^{\infty} Y_k L_k(t), \quad t \in [0, 1],$$

where

- $\{Y_n\}_{n \in \mathbb{N}}$ is the sequence of i.i.d. $N(0, 1)$ -distributed random variables;
- $L_k(t) = \int_0^t H_k(s) ds$ are the **Schauder functions** and H_k are the **Haar functions**, $k \in \mathbb{N}$.

This series converges (a.s.) absolutely and uniformly on $[0, 1]$.

Approximation of the Wiener sausage



- Haar functions: $H_1(s) = 1, s \in [0, 1],$

$$H_{2^m+k}(s) = \begin{cases} 2^{\frac{m}{2}}, & s \in \left[\frac{k-1}{2^m}, \frac{2k-1}{2^{m+1}} \right), \\ -2^{\frac{m}{2}}, & s \in \left[\frac{2k-1}{2^{m+1}}, \frac{k}{2^m} \right), \\ 0, & \text{otherwise} \end{cases}, \quad \begin{aligned} k &= 1, 2, \dots, 2^m, \\ m &= 0, 1, 2, \dots \end{aligned}$$

Approximation of the Wiener sausage

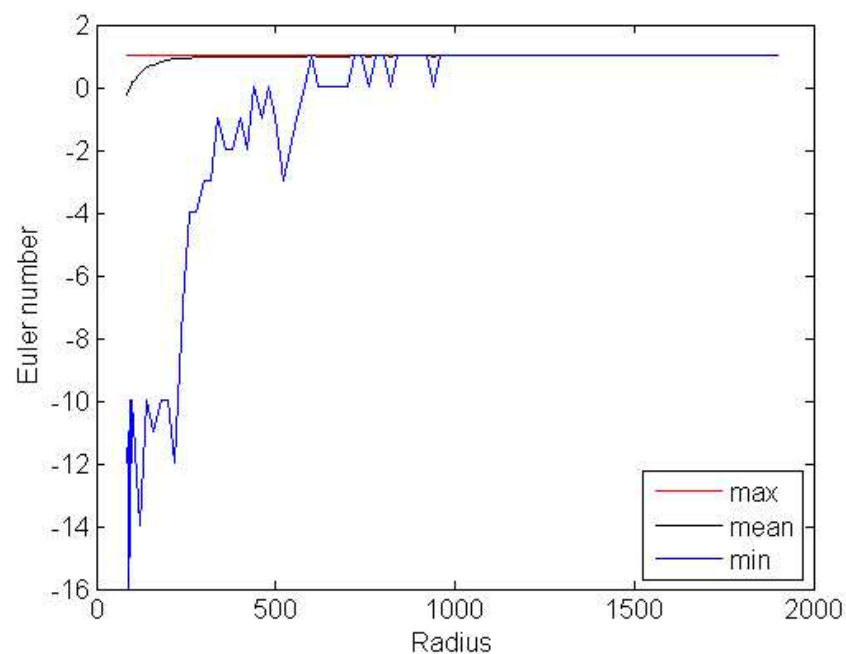
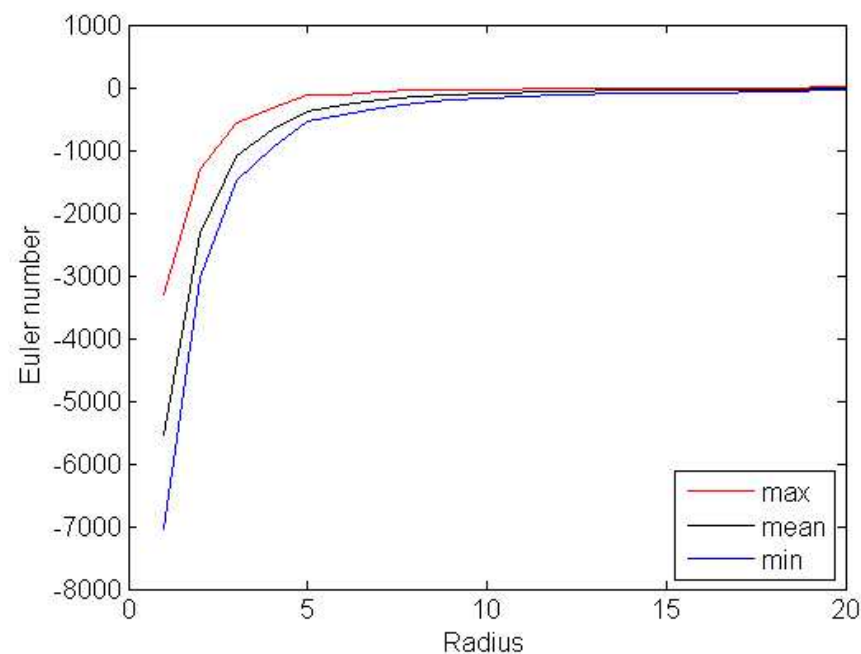
- Approximate the Brownian motion $X(t)$ by $X^n(t) = (W_1^n(t), \dots, W_d^n(t))$, $t \in [0, 1]$, where

$$W_i^n(t) = \sum_{k=1}^{2^n} Y_{ik} L_k(t), \quad t \in [0, 1],$$

and Y_{ik} are i.i.d. $N(0, 1)$ random variables.

- The path $S^n = \{X^n(t) : 0 \leq t \leq 1\}$ is a piecewise linear curve with $2^n + 1$ nodes lying on $S = \{X(t) : 0 \leq t \leq 1\}$.

Approximation formula for $\mathbb{E} V_0(S_r)$ in 2D

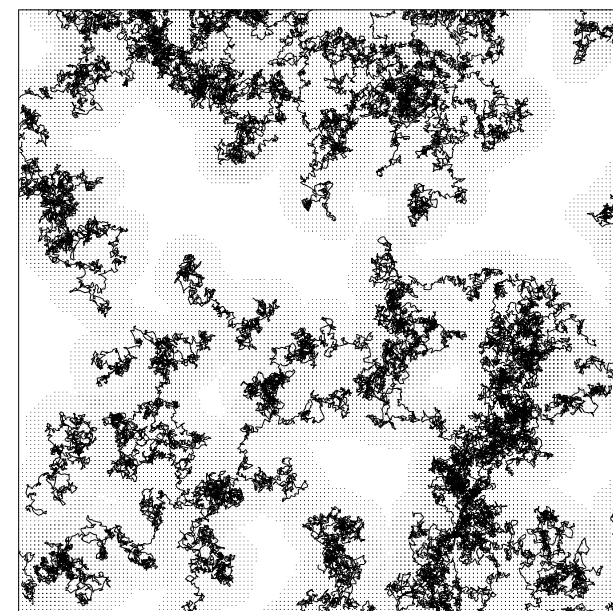
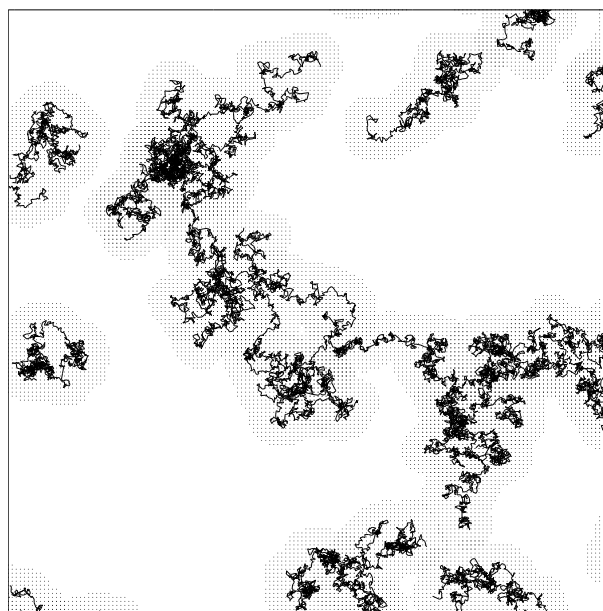
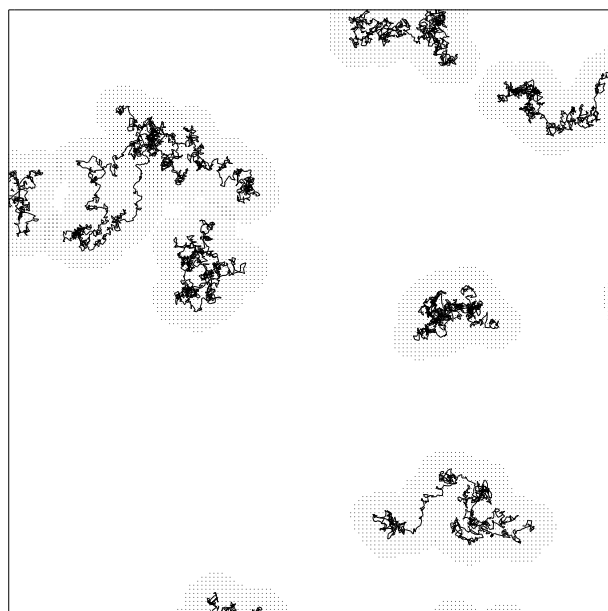


$$\mathbb{E} V_0(S_r) \approx 1 + \frac{0.0423017 \left(1 - \Phi\left(\frac{r-224.899}{50.2096}\right)\right)}{\log\left(3.88182 \cdot 10^{-6} r^{1.88978} + 1.0\right) r^{0.153452}},$$

where Φ is the c.d.f of $N(0,1)$ – distribution.

Boolean model of Wiener sausages

$\Xi = \bigcup_{i \in \mathbb{N}} (x_i + (S_r)_i)$ where $\{x_i\}$ is a stationary Poisson point process of germs with intensity $\lambda > 0$ and grains $(S_r)_i$ are iid copies of S_r .



Three realizations with volume fractions 0.25, 0.5 and 0.75 ($T = 10$, $r = 1$)

Capacity functional

- Definition and formula

$$T_{\Xi}(C) = P(\Xi \cap C \neq \emptyset) = 1 - e^{-\lambda \mathbb{E} |S_r \oplus \check{C}|}$$

for all compact C , where

$$\mathbb{E} |S_r \oplus \check{C}| = \int_{\mathbb{R}^d} P(x \in S_r \oplus \check{C}) dx = \int_{\mathbb{R}^d} P(\tau_{C \oplus B_r(o)}^x \leq T) dx .$$

$\tau_A^x = \inf\{s \geq 0 : X^x(s) \in A\}$ is the **first hitting time** of a Borel set A for the Brownian motion starting at $x \in \mathbb{R}^d$.

- Notation:** $u(t, x) = P(\tau_{C \oplus B_r(o)}^x \leq t)$, $x \in \mathbb{R}^d$, $t \geq 0$

Capacity functional

Kolmogoroff and Leontowitsch (1933), Doob (1955), Hunt (1956)

$u(t, x)$ is the unique bounded solution to the following heat conduction problem:

$$\frac{\partial u}{\partial t} = \frac{\sigma^2}{2} \Delta u, \quad t > 0, x \in \mathbb{R}^d \setminus (C \oplus B_r(o)),$$

$$u(0, x) = 0, \quad x \in \mathbb{R}^d \setminus (C \oplus B_r(o)),$$

$$u(t, x) = 1, \quad t \geq 0, \text{ for all regular } x \in \partial(C \oplus B_r(o)),$$

i.e. points x such that $P \left(\tau_{C \oplus B_r(o)}^x = 0 \right) = 1$. In general, this problem has to be solved **numerically**.

Volume fraction

- Explicit solution: $C = \{o\}$.

For

$$p_{\Xi} = P(o \in \Xi) = \mathbb{E} |\Xi \cap [0, 1]^d| = T_{\Xi}(\{o\})$$

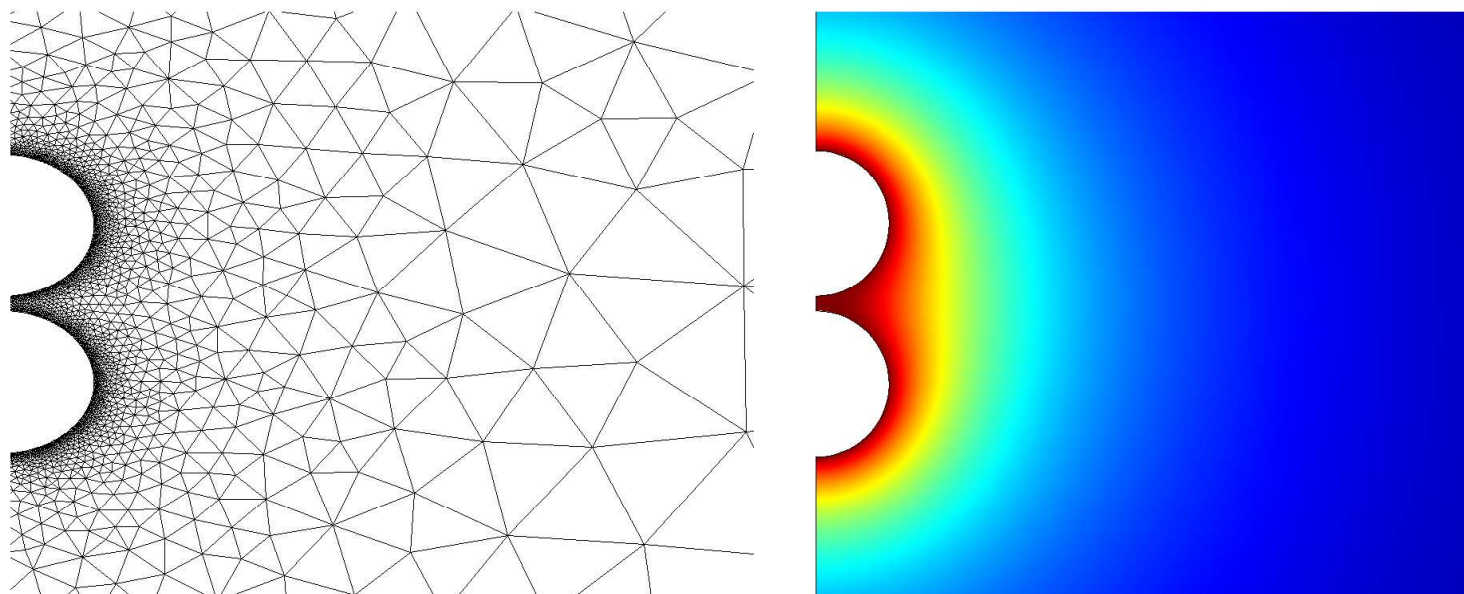
we get

$$p_{\Xi} = 1 - e^{-\lambda \left(\omega_d r^d + \frac{d(d-2)}{2} \omega_d \sigma^2 r^{d-2} T + \frac{4d \omega_d r^d}{\pi^2} \int_0^{\infty} \frac{1 - e^{-\frac{\sigma^2 y^2 T}{2r^2}}}{y^3 (J_{\nu}^2(y) + Y_{\nu}^2(y))} dy \right)}.$$

Covariance function

- Numerical solution: $C = \{o, h \cdot u\}$, where $u \in \mathcal{S}^{d-1}$ and $h \geq 0$.

$$C_{\Xi}(h) = P(o, h \cdot u \in \Xi) = 2p_{\Xi} - T_{\Xi}(\{o, h \cdot u\})$$



Finite element method: mesh (left) and computed solution u (right) for

$$d = 2, \sigma^2 = 1, r = 1, h = 2.2 \text{ and } t = 100.$$

Covariance function

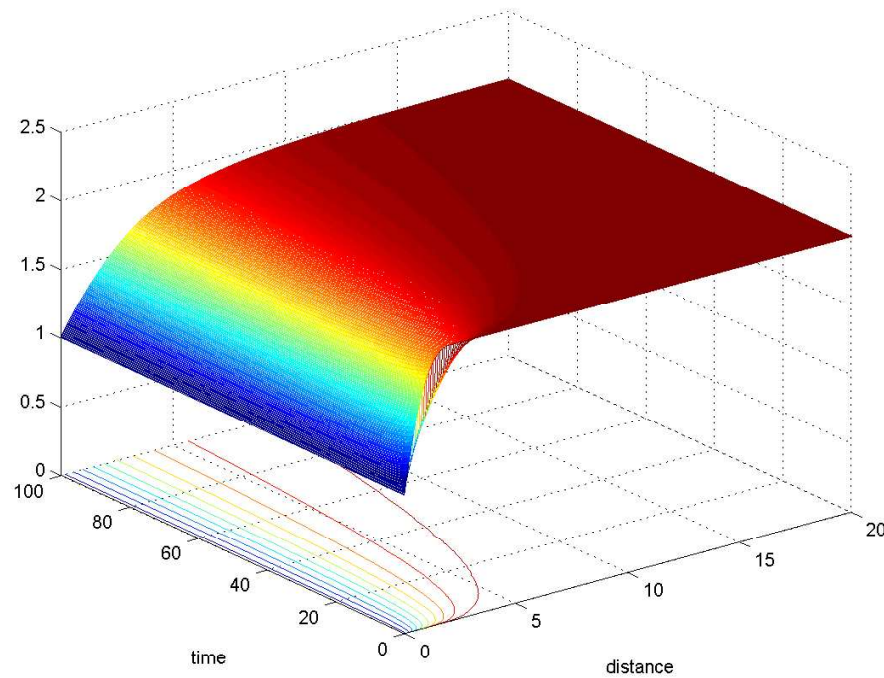
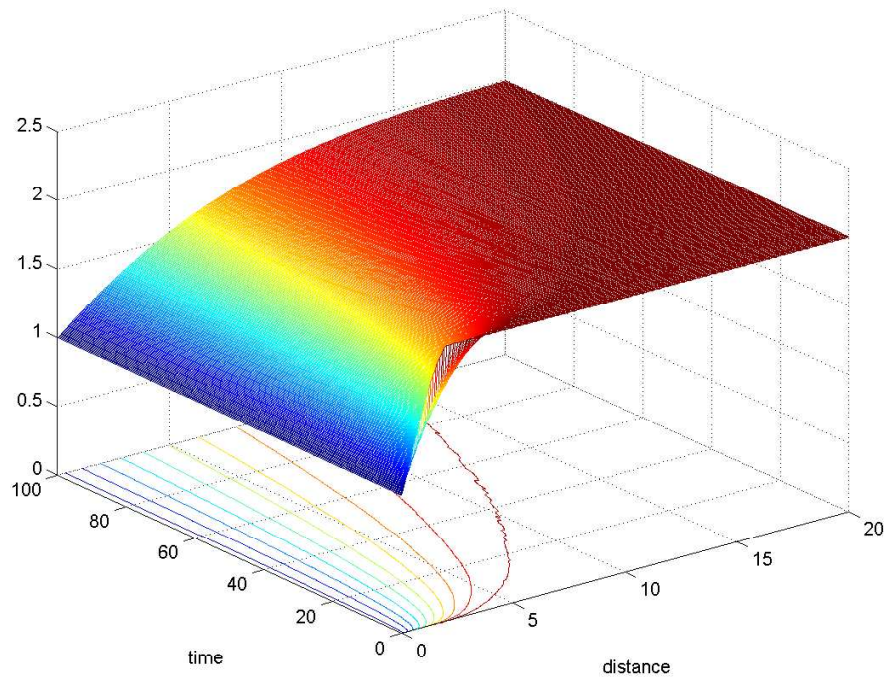
Approximation formula (CFS 08). Let $r = 1$, $\sigma^2 = 1$.

$$C_{\Xi}(h) \approx 2p_{\Xi} - 1 + (1 - p_{\Xi})^{\kappa(h,t)},$$

$$\kappa(h,t) = \begin{cases} \frac{2}{\pi} \left(\pi - \arccos\left(\frac{h}{2r}\right) + \frac{h}{2r} \sqrt{1 - \frac{h}{2r}} \right), & h \leq 2r, t = 0, d = 2, \\ \frac{1}{2} \left(\frac{h}{2r}\right)^3 - 2 \left(\frac{h}{2r}\right)^2 + \frac{5}{2} \frac{h}{2r} + 1, & h \leq 2r, t = 0, d = 3, \\ \left(\frac{h}{\nu(t)}\right)^3 - 3 \left(\frac{h}{\nu(t)}\right)^2 + 3 \frac{h}{\nu(t)} + 1, & h \leq \nu(t), t > 0, d = 2, 3, \\ 2, & \text{otherwise,} \end{cases}$$

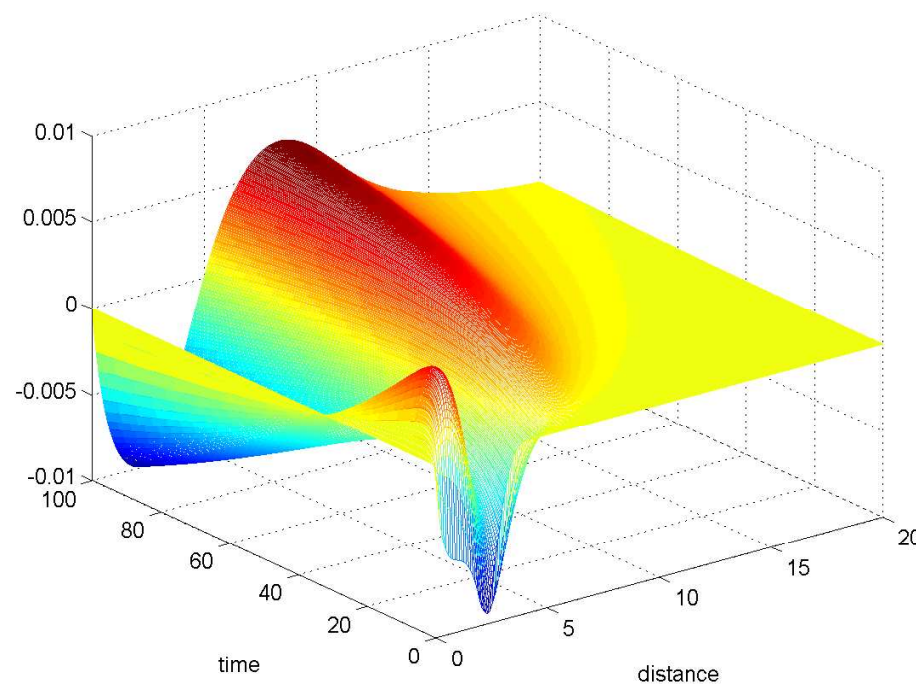
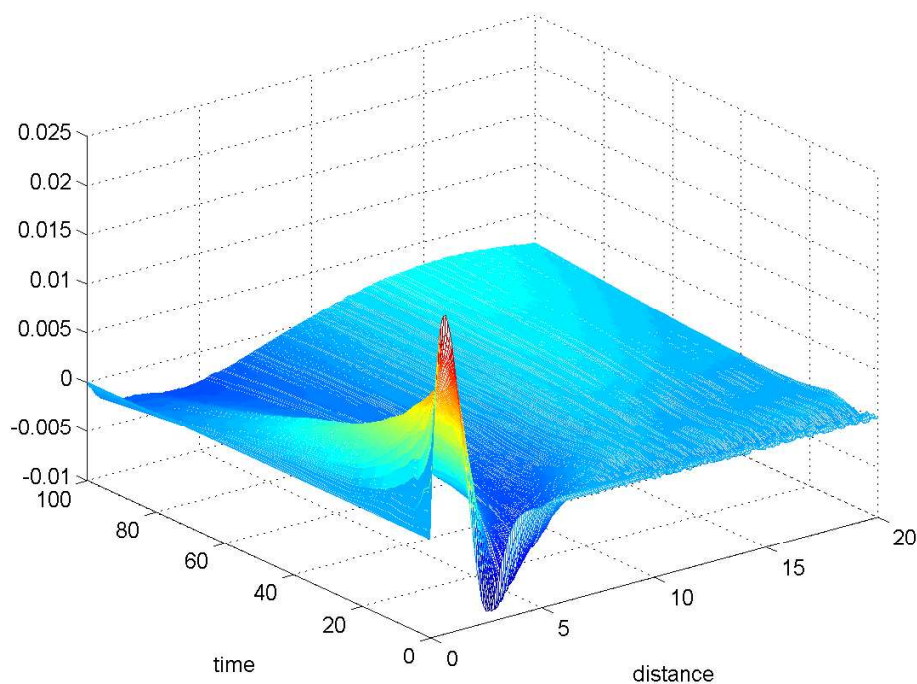
$$\nu(t) = \begin{cases} 3.124 t^{0.3925} + 2.794, & d = 2, \\ 3.744 t^{0.2182} + 1.454, & d = 3. \end{cases}$$

Covariance function



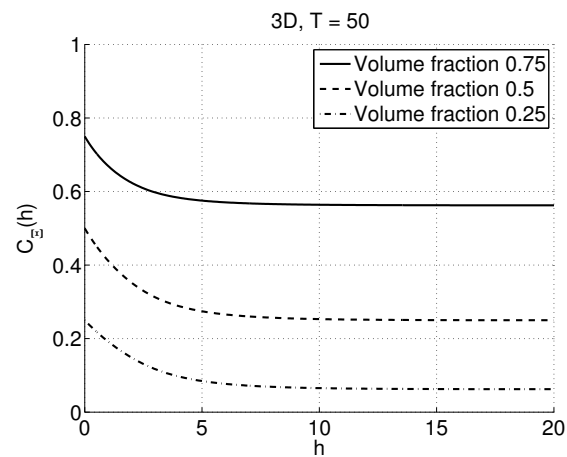
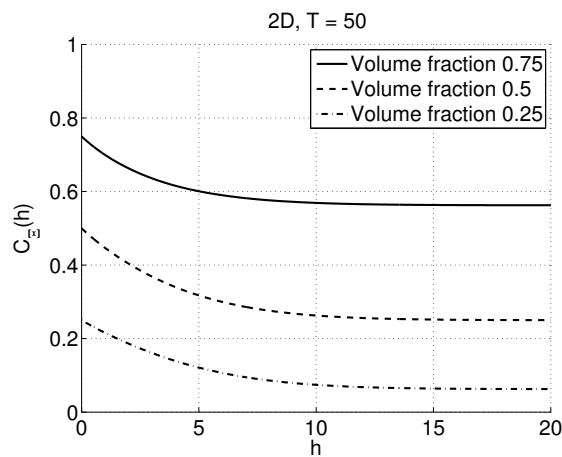
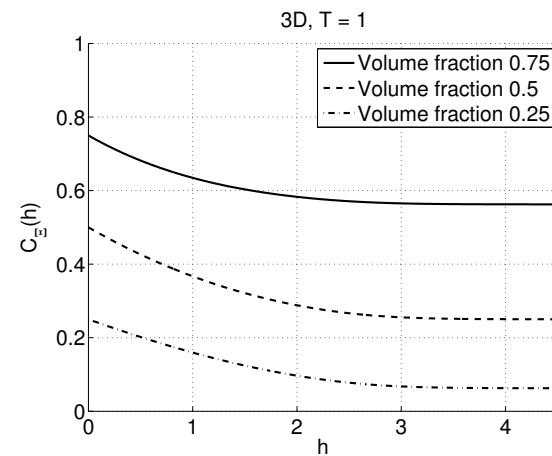
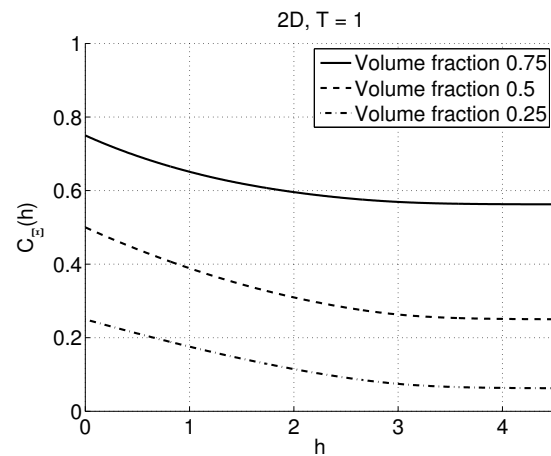
$\kappa(h, t)$ in 2D (left) resp. 3D (right) for $r = 1$, $0 \leq h \leq 20$ and $0 \leq t \leq 100$

Covariance function



Relative approximation errors in 2D (left) resp. 3D (right) for $p_{\Xi} = 0.75$, $r = 1$,
 $0 \leq h \leq 20$ and $0 \leq t \leq 100$.

Covariance function



$C_{\Xi}(h)$ with $r = 1$, $\sigma^2 = 1$ and $T = 1$, $T = 50$.

Spherical contact distribution function

$$H_{B_1(o)}(\rho) = P(\Xi \cap B_\rho(o) \neq \emptyset \mid o \notin \Xi) = \frac{T_\Xi(B_\rho(o)) - T_\Xi(\{o\})}{1 - T_\Xi(\{o\})}.$$

It holds

$$H_{B_1(o)}(\rho) = 1 - e^{-\lambda M(d, \sigma^2, r, \rho, T)},$$

where

$$M(d, \sigma^2, r, \rho, T) = \omega_d ((r + \rho)^d - r^d) + \frac{d(d-2)}{2} \omega_d \sigma^2 ((r + \rho)^{d-2} - r^{d-2}) T + \frac{4d\omega_d}{\pi^2} \left((r + \rho)^d \int_0^\infty \frac{1 - e^{-\frac{\sigma^2 y^2 T}{2(r+\rho)^2}}}{y^3 (J_\nu^2(y) + Y_\nu^2(y))} dy - r^d \int_0^\infty \frac{1 - e^{-\frac{\sigma^2 y^2 T}{2r^2}}}{y^3 (J_\nu^2(y) + Y_\nu^2(y))} dy \right).$$

Specific surface area

- Specific surface area of Ξ

Constant $S_{\Xi} \in (0, \infty)$ defined by

$$S_{\Xi}(B) = \mathbb{E} \mathcal{H}^{d-1}(\partial\Xi \cap B) = S_{\Xi} \cdot |B|$$

for all Borel sets $B \subset \mathbb{R}^d$, $d = 2, 3$.

- For $d = 2, 3$ it holds

$$S_{\Xi} = \lambda \mathbb{E} \mathcal{H}^{d-1}(\partial S_r) e^{-\lambda \mathbb{E} |S_r|}, \quad r > 0.$$

- Example: $d = 3$

$$S_{\Xi} = 2\pi\lambda \left(2r^2 + 4r\sigma\sqrt{2T/\pi} + \sigma^2 T \right) e^{-2\pi\lambda r \left(2/3r^2 + 2\sigma r\sqrt{2T/\pi} + \sigma^2 T \right)}.$$

Outlook

- Formula for $E\mathcal{H}^{d-1}(\partial S_r)$ for **all** $r > 0$ ($d \geq 4$)
- Formulae for $\mathbb{E} V_j(S_r)$, $j \leq d - 2$ and **specific intrinsic volumes** $\bar{V}_j(\Xi)$, $j \leq d - 2$ of the Boolean model of Wiener sausages
- **Limit theorems** for the surface area $\mathcal{H}^{d-1}(\partial S_r)$ and other intrinsic volumes $V_j(S_r)$ of the shrinking Wiener sausage
LT for the volume (J.-F. Le Gall (1988)): for $d = 2$, it holds

$$(\log r)^2(|S_r| + \pi / \log r) \xrightarrow{w} c - \pi^2 \gamma, \quad r \rightarrow 0,$$

where $\sigma^2 = T = 1$ and γ is the (renormalized) Brownian local time of self-intersections. For $d \geq 3$: CLT.

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