# A dynamic approach to heterogeneous elastic wires

Anna Dall'Acqua (Ulm University) Leonie Langer (Ulm University) Fabian Rupp (University of Vienna)

#### Model

Model a heterogeneous elastic wire by a closed planar **curve**  $\gamma$  with **density**  $\rho$ . Extending [1], the energy of the wire is

$$\mathcal{L}_{\mu}(\gamma,\rho) = \frac{1}{2} \int_{\gamma} \left( \beta(\rho)(\kappa - c_0)^2 + \mu \left(\partial_s \rho\right)^2 \right) \mathrm{d}s \tag{1}$$

with the arc-length parameter sand the curvature  $\kappa$  of  $\gamma$ . Model parameters:



## Nonlocal Lagrange multipliers

**Closedness-constraint:** Lagrange multipliers  $\lambda_{\theta 1}$  and  $\lambda_{\theta 2}$ . Define  $\begin{pmatrix} \lambda_{\theta 1}(t) \\ \lambda_{\theta 2}(t) \end{pmatrix} := \Pi^{-1}(\theta)(t) \int_0^L \begin{pmatrix} -\sin \theta \\ \cos \theta \end{pmatrix} \partial_s (\beta(\rho)(\partial_s \theta - c_0)) \mathrm{d}s,$ where  $\Pi^{-1}(\theta)(t)$  denotes the inverse of the matrix  $\Pi(\theta)(t) := \begin{pmatrix} \int_0^L \sin^2 \theta \, \mathrm{d}s & -\int_0^L \cos \theta \sin \theta \, \mathrm{d}s \\ -\int_0^L \cos \theta \sin \theta \, \mathrm{d}s & \int_0^L \cos^2 \theta \, \mathrm{d}s \end{pmatrix}.$ 

This ensures (2) along the flow.

density-modulated bending stiffness β ∈ C<sup>∞</sup>(ℝ), β > 0,
spontaneous curvature c<sub>0</sub> ∈ ℝ,

• diffusivity  $\mu > 0$  of the density.

Figure 1: Visualisation of a heterogeneous wire with  $c_0 \neq 0$ .

This energy is invariant under orientation-preserving reparametrizations.

**Fixed total mass-constraint:** Lagrange multiplier  $\lambda_{\rho}$ . With

 $\lambda_{\rho}(t) := -\frac{1}{2L} \int_0^L \beta'(\rho) (\partial_s \theta - c_0)^2 \,\mathrm{d}s,$ 

a solution  $(\theta, \rho)$  satisfies (4).

### **Order reduction**

Describe the arclength-parametrization  $\gamma \colon [0, L] \to \mathbb{R}^2$  by an inclination angle function  $\theta \colon [0, L] \to \mathbb{R}$  such that

 $\partial_s \gamma = \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix}.$ 



Figure 2: Angle function  $\theta$ .

The angle function  $\theta$  represents a  $C^1$ -closed curve if and only if

 $\int_{0}^{L} \cos\theta \,\mathrm{d}s = \int_{0}^{L} \sin\theta \,\mathrm{d}s = 0 \quad \text{and} \quad \theta(L) - \theta(0) = 2\pi\omega, \quad (2)$ 

for some  $\omega \in \mathbb{Z}$ , the rotation index of the curve.

 $\mathbf{T} \qquad (\mathbf{1}) \cdot \mathbf{I} \qquad \mathbf{C} \cap [\mathbf{0} \mathbf{T}] \quad \mathbf{T} \qquad \mathbf{1} \quad [\mathbf{0} \mathbf{T}] \quad \mathbf{T}$ 

## Local well-posedness

**Theorem 1 ([2]).** Let  $(\theta_0, \rho_0) \in h^{1+\alpha}([0, L])$  (little Hölder space) for some  $\alpha \in (0, 1)$  such that  $\theta_0(L) - \theta_0(0) = 2\pi\omega, \quad \partial_s\theta_0(L) = \partial_s\theta_0(0),$  $\rho_0(L) = \rho_0(0), \qquad \partial_s\rho_0(L) = \partial_s\rho_0(0)$ and  $\theta_0$  satisfies (2). Then there exist  $T_0 > 0$  and a unique solution  $(\theta, \rho) \in C^{\infty}((0, T_0) \times [0, L])$ of (5) on  $(0, T_0) \times [0, L]$  satisfying the initial condition in the sense that

 $\lim_{t \to 0} (\theta(t), \rho(t)) = (\theta_0, \rho_0) \quad \text{in } C^{1+\alpha}([0, L]).$ 

Express (1) in terms of 
$$\theta: [0, L] \to \mathbb{R}$$
 and  $\rho: [0, L] \to \mathbb{R}$  by  

$$E_{\mu}(\theta, \rho) = \frac{1}{2} \int_{0}^{L} \left( \beta(\rho)(\partial_{s}\theta - c_{0})^{2} + \mu (\partial_{s}\rho)^{2} \right) \mathrm{d}s, \qquad (3)$$
using that  $\kappa = \partial_{s}\theta$ .

## Goal

Use a dynamic approach to minimize (3) by evolving  $(\theta, \rho)$  by the associated  $L^2$ -gradient flow. Thereby, require that

• the curve  $\gamma$  remains  $C^2$ -closed,

• the density  $\rho$  remains  $C^1$ -periodic and  $\int_0^L \rho \, \mathrm{d}s = \int_0^L \rho_0 \, \mathrm{d}s.$  (4)

 $\begin{aligned} \partial_t \theta &= \partial_s \left( \beta(\rho) (\partial_s \theta - c_0) \right) + \lambda_{\theta 1} \sin \theta - \lambda_{\theta 2} \cos \theta & \text{ in } (0, T) \times [0, L], \\ \partial_t \theta &= \partial_s \left( \beta(\rho) (\partial_s \theta - c_0) \right) + \lambda_{\theta 1} \sin \theta - \lambda_{\theta 2} \cos \theta & \text{ in } (0, T) \times [0, L], \end{aligned}$ 

Moreover, the solution depends continuously on the initial datum.

#### Idea of the proof

**Local Existence:** Transform (5) to an equivalent problem in a periodic setting to get rid of the boundary conditions. Apply the Inverse Function Theorem between appropriate time-weighted Hölder spaces.

**!!** Working with time-weights makes the arguments more challenging, but provides well-posedness for weak initial data.

#### **Global existence**

**Theorem 2 ([2]).** The unique smooth solution  $(\theta, \rho)$  of Theorem 1 exists up to  $T = \infty$  and subconverges to a stationary solution of (5).

$\partial_t \rho = \mu \partial_s^2 \rho - \frac{1}{2} \beta'(\rho) (\partial_s \theta - c_0)^2 - \lambda_\rho$		in $(0, T') \times [0, L],$	
$\theta(\cdot, L) - \theta(\cdot, 0) = 2\pi\omega,$	$\rho(\cdot,L)=\rho(\cdot,0)$	on $[0, T)$ ,	
$\partial_s \theta(\cdot, L) = \partial_s \theta(\cdot, 0),$	$\partial_s \rho(\cdot, L) = \partial_s \rho(\cdot, 0)$	on $[0, T)$ ,	
$\theta(0,\cdot)=\theta_0,$	$\rho(0,\cdot)=\rho_0$	on $[0, L]$	(5)

C The L<sup>2</sup>-gradient flow is a quasilinear coupled parabolic system that is nonlocal due to the Lagrange multipliers λ<sub>θ1</sub>, λ<sub>θ2</sub> and λ<sub>ρ</sub>.
C Working with the angle function θ reduces the order of the equation for γ from fourth to second order.



Figure 3: Numerical experiments on the convergence (thickness and color of the curve describe  $\rho$ ) by Gaspard Jankowiak, University of Constance.



**References:** 

[1] Brazda, Jankowiak, Schmeiser, Stefanelli. *Bifurcation of elastic curves with modulated stiffness*. Europ. J. of Appl. Math. (2022)
 [2] Dall'Acqua, Langer, Rupp, *A dynamic approach to heterogeneous elastic wires*. arXiv:2205.06587 (2022)

