



Prof. Dr. Stefan Funken  
M.Sc. Mladjan Radic, Stefan Hain  
Department of Numerical Mathematics  
Ulm University

Numerik von gewöhnlichen Differenzialgleichungen  
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## Sheet 10

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### Exercise 1 (Well-posedness)

Explain what is wrong in both the variational setting and the classical setting for the following BVP:

$$\begin{aligned} -u''(x) &= f(x), & x \in (0, 1), \\ u'(0) &= u'(1) = 0. \end{aligned}$$

More precise: Explain in both contexts why this problem is not well-posed with respect to  $H^1(\Omega)$ .

### Exercise 2 (Graduated Grids)

Let the exact solution of a given BVP be given by  $u(x) = x^\alpha$  for  $\alpha > \frac{1}{2}$  on  $\Omega = (0, 1)$ . Let  $u_I(x)$  be the linear interpolant of  $u$  on a given grid  $\mathcal{T} := \{0 = x_0 < x_1 < \dots < x_N < x_{N+1} = 1\}$ , i.e.  $u_I \in \mathcal{S}^{1,1}(\mathcal{T})$  and on a given element  $(u_i, u_{i+1})$ ,  $u_I(x)$  may be expressed by

$$u_I(x) = u(x_{i+1}) \cdot \frac{x_{i+1} - x}{x_{i+1} - x_i} + u(x_i) \cdot \frac{x - x_i}{x_{i+1} - x_i} = x_{i+1}^\alpha \cdot \frac{x_{i+1} - x}{x_{i+1} - x_i} + x_i^\alpha \cdot \frac{x - x_i}{x_{i+1} - x_i}.$$

We define the error  $e(x) := u(x) - u_I(x)$ . Compute the error in the  $H^1$ -semi-norm  $|e(x)|_{H^1(\Omega)}$ , in the  $L_2$ -norm  $\|e(x)\|_{L_2(\Omega)}$  and in the  $H^1$ -norm  $\|e(x)\|_{H^1(\Omega)} = \sqrt{\|e(x)\|_{L_2(\Omega)}^2 + |e(x)|_{H^1(\Omega)}^2}$  for the following grids:

- (i)  $\mathcal{T} := \{x_i \mid x_i := \frac{i}{N}, \quad i = 0, \dots, N\}$ , (equidistant grid),
- (ii)  $\mathcal{T} := \{x_i \mid x_i := (\frac{i}{N})^\beta, \quad i = 0, \dots, N\}$ , (graduated grid),

by choosing  $\beta = \frac{1}{\alpha - \frac{1}{2}}$ ,  $\beta = \frac{1}{\alpha}$ ,  $\beta = \frac{1}{\alpha + \frac{1}{2}}$ ,  $\beta = \frac{5}{\alpha - \frac{1}{2}}$ ,  $\alpha \in \{\frac{3}{4}, 1, 2, 5\}$  and  $N := \{10^0, 10^1, 10^2, 10^3, 10^4, 10^5\}$ . What do you observe? What have you expected? In matlab you can use the command `x = linspace(0,1,N+1)` to obtain an equidistant grid. What happens if you use `x = logspace(0,1,N+1)` instead and use this as another graduated grid? Plot the error for the above mentioned grids.

**Hint:** You can use the following equations to implement the norm of the error:

$$\|e(x)\|_{L_2(\Omega)}^2 = \int_{\Omega} (u(x) - u_I(x))^2 dx = \sum_{i=0}^N \int_{x_i}^{x_{i+1}} (u(x) - u_I(x))^2 dx.$$

and analogously

$$|e(x)|_{H^1(\Omega)}^2 = \int_{\Omega} (u'(x) - u'_I(x))^2 dx = \sum_{i=0}^N \int_{x_i}^{x_{i+1}} (u'(x) - u'_I(x))^2 dx.$$

### Exercise 3 (FEM)

We consider the following BVP

$$\begin{aligned} - (a(x)u'(x))' + b(x)u'(x) + c(x)u(x) &= f(x), & x \in \Omega = (0, 1) \\ u(0) = \alpha, & \quad u(1) = \beta \end{aligned} \tag{1}$$

Show, that the variational formulation (for  $\alpha = \beta = 0$ ) is given by: Find  $u \in V := H_0^1(\Omega)$ , such that

$$\int_{\Omega} a(x)u'(x)v'(x) dx + \int_{\Omega} b(x)u'(x)v(x) dx + \int_{\Omega} c(x)u(x)v(x) dx = \int_{\Omega} f(x)v(x) dx$$

for all  $v \in V$ . In this sheet, we want to consider another strategy for the implementation of this more general equation and a slightly different strategy for assembling the stiffness matrix. The 1d-grid should be stored in the matrices `coordinates`  $\in \mathbb{R}^{n_C \times 1}$  and `elements`  $\in \mathbb{R}^{n_E \times 2}$ . The matrix `coordinates` contains the coordinates of the grid points and `elements` contains the indices for the edge points of each interval. Let us at first consider the interval  $(0, 1)$ , which is partitioned in only two elements, i.e.  $E_1 = (0, \frac{1}{2}) = (x_1, x_2)$  and  $E_2 = (\frac{1}{2}, 1) = (x_2, x_3)$ . It is then clear, that the corresponding matrices are `coordinates`  $= \begin{pmatrix} 0 & 0.5 & 1 \end{pmatrix}^T$  and `elements`  $= \begin{pmatrix} 1 & 2 \\ 2 & 3 \end{pmatrix}^T$ . We have already seen, that for the Laplace problem, i.e.  $a(x) = 1, b(x) = c(x) = 0$  and with  $h_1 = x_1 - x_2 = \frac{1}{2}, h_2 = x_3 - x_2 = \frac{1}{2}$ , we obtain the very small stiffness-matrix (by using the hat functions):

$$A = \begin{pmatrix} 2\frac{1}{h_1} & -\frac{1}{h_1} & 0 \\ -\frac{1}{h_1} & \frac{1}{h_1} + \frac{1}{h_2} & -\frac{1}{h_2} \\ 0 & -\frac{1}{h_2} & 2\frac{1}{h_2} \end{pmatrix} = \begin{pmatrix} 2\frac{1}{h_1} & -\frac{1}{h_1} & 0 \\ -\frac{1}{h_1} & \frac{1}{h_1} & 0 \\ 0 & 0 & 0 \end{pmatrix} + \begin{pmatrix} 0 & 0 & 0 \\ 0 & \frac{1}{h_2} & -\frac{1}{h_2} \\ 0 & -\frac{1}{h_2} & 2\frac{1}{h_2} \end{pmatrix}$$

which is now our first motivation for assembling the stiffness matrix element-wise. As we now see above, we just need to compute smaller  $2 \times 2$ -matrices and afterwards summing them up with respect to the corresponding position. The next motivation for assembling the smaller  $2 \times 2$ -matrices is, that we do not have to number the nodes lexicographically, i.e.  $x_1 = 0, x_3 = 0.5, x_2 = 1$ , which ends up in  $E_1 = (0, \frac{1}{2}) = (x_1, x_3)$  and  $E_2 = (\frac{1}{2}, 1) = (x_3, x_2)$  and `coordinates`  $= \begin{pmatrix} 0 & 0.5 & 1 \end{pmatrix}^T$  and `elements`  $= \begin{pmatrix} 1 & 3 \\ 3 & 2 \end{pmatrix}^T$ . And the corresponding matrix is now given by

$$A = \begin{pmatrix} 2\frac{1}{h_1} & 0 & -\frac{1}{h_1} \\ 0 & 2\frac{1}{h_2} & -\frac{1}{h_2} \\ -\frac{1}{h_1} & -\frac{1}{h_2} & \frac{1}{h_1} + \frac{1}{h_2} \end{pmatrix} = \begin{pmatrix} 2\frac{1}{h_1} & 0 & -\frac{1}{h_1} \\ 0 & 0 & 0 \\ \frac{1}{h_1} & 0 & \frac{1}{h_1} \end{pmatrix} + \begin{pmatrix} 0 & 0 & 0 \\ 0 & 2\frac{1}{h_2} & -\frac{1}{h_2} \\ 0 & -\frac{1}{h_2} & \frac{1}{h_2} \end{pmatrix}$$

This demonstrates, that we have to compute 4 entries on each element and afterwards just summing them up with respect to their position. This will be now discussed in more detail.

(a) Draw the grid for

$$\begin{aligned} \text{coordinates} &= \begin{pmatrix} 0 & 0.5 & 0.3 & 0.6 & 1.0 & 0.9 \end{pmatrix}^T \\ \text{elements} &= \begin{pmatrix} 1 & 3 & 2 & 4 & 6 \\ 3 & 2 & 4 & 6 & 5 \end{pmatrix}^T \end{aligned}$$

The vector `dirichlet` contains the indices for the Dirichlet nodes, in our case this vector is given by `dirichlet`  $= \begin{pmatrix} 1 & 5 \end{pmatrix}^T$ .

We want to consider now the uniform refinement of the grid. Each element will be halved. The procedure is then as follows:

(1) For each element compute the midpoint and store the coordinate of these midpoints at the end of the vector. In the above example, where we have considered the tow elements  $E_1 = (0, \frac{1}{2}) = (x_1, x_2)$  and  $E_2 = (\frac{1}{2}, 1) = (x_2, x_3)$ , we compute the new midpoints  $x_4 = 0.25$  and  $x_5 = 0.75$ . Therefore we obtain  $\text{coordinates} = (0 \ 0.5 \ 1 \ 0.25 \ 0.75)^T$

(2) Compute the new elements. In our example, we would obtain  $\text{elements} = \begin{pmatrix} 1 & 4 & 2 & 5 \\ 4 & 2 & 5 & 3 \end{pmatrix}$ .

With the help of Matlab, this procedure can be realized very efficient.

(b) Compute the matrices `coordinates` and `elements` for the refined grid in (a). Implement a function

`[coordinates,elements] = function refineMesh(coordinates,elements)`

which realized the refinement of a given grid as described above.

The next step is the assemblation of the stiffness matrix and this will be done element-wise, as we already tried to describe above. Consider the  $j$ -th element  $T_j = [x_j, x_{j+1}]$  of the given grid. On  $T_j$  we only have to consider  $\varphi_j$  and  $\varphi_{j+1}$ , because all other functions vanish. For the  $j$ -th element we compute the small  $2 \times 2$  matrix

$$\begin{pmatrix} \int_{T_j} a(x) \cdot \varphi_j'(x) \cdot \varphi_j'(x) dx & \int_{T_j} a(x) \cdot \varphi_j'(x) \cdot \varphi_{j+1}'(x) dx \\ \int_{T_j} a(x) \cdot \varphi_{j+1}'(x) \cdot \varphi_j'(x) dx & \int_{T_j} a(x) \cdot \varphi_{j+1}'(x) \cdot \varphi_{j+1}'(x) dx \end{pmatrix}.$$

This  $2 \times 2$  matrix will then be added on the corresponding position. Note, that we have set  $b(x) = c(x) = 0$ .

(c) Visualize this procedure on a sheet of paper with (a).

The right-hand side of the equation will also be computed element-wise.

(d) Write a function `[A,B,C,b] = assemble(coordinates,elements,f)`, which assembles the matrices  $A$ ,  $B$  and  $C$  and the right-hand side  $b$  element-wise. `f` is a function-handle for the right-hand side of the equation. Note, that  $A$  is the matrix associated to the diffusion-term  $\int_{\Omega} a(x)u'(x)v'(x) dx$ ,  $B$  is the matrix associated to the convection term  $\int_{\Omega} b(x)u'(x)v(x) dx$  and  $C$  is the matrix associated to the reaction term  $\int_{\Omega} c(x)u(x)v(x) dx$ .

(e) Complete the script `main.m`, which is given on the home-page. In this script, the grid is loaded and the BVP (1) is solved numerically. It is assumed, that  $a(x), b(x), c(x)$  are constant in  $\Omega = (0, 1)$ . Test your implementation with the following BVPs

- (i)  $a = 1, b = 0, c = 0, f = 1$  and  $u(0) = u(1) = 0$ ,
- (ii)  $a = 1, b = 0, c = 0, f = 1$  and  $u(0) = 0, u(1) = 1$ ,
- (iii)  $a = 1, b = 0, c = 0, f = x$  and  $u(0) = u(1) = 0$ ,
- (iv)  $a = 1, b = 0, c = 1/100, f = 1$  and  $u(0) = u(1) = 0$ ,
- (v)  $a = 1, b = 1/10, c = 0, f = 1$  and  $u(0) = u(1) = 0$ .