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### Sheet 3

Due May 12, 2016.

#### Exercise 1 (Consistency and Increment Function)

Consider the IVP

$$\begin{aligned}y'(t) &= f(t, y(t)), & t \in I := [0, T] \subset \mathbb{R}, \\y(0) &= y_0.\end{aligned}\tag{1}$$

Let  $h > 0$  be the step-size. Every one-step method for determination of the grid-function  $\{y_m\}_{m=1}^N$  is of the form

$$y_{m+1} = y_m + h\Phi(t_m, y_m; h), \quad m = 0, \dots, N-1,$$

where  $\Phi$  is the so called *increment function*.

- (a) Determine the increment function for the explicit and implicit Euler method.  
(b) Let  $y \in C^1(I)$  be the exact solution of the IVP (1). Show: A one-step method is consistent if and only if

$$\lim_{h \rightarrow 0} \Phi(t, y(t); h) = f(t, y(t)).$$

Use this result to justify why the explicit and implicit Euler method are consistent.

- (c) Let  $f \in C^2(I \times \mathbb{R})$ . Consider the increment function

$$\Phi(t, y; h) = \alpha_1 f(t, y) + \alpha_2 f(t + \beta_1 h, y + \beta_2 h f(t, y)).$$

Determine  $\alpha_1, \alpha_2, \beta_1, \beta_2 \in \mathbb{R}$  such that the order of convergence equals 2. Is it possible to achieve higher order?

- (d) Let  $f \in C^3(I \times \mathbb{R})$ . Consider the increment function

$$\Phi(t, y; h) = \frac{1}{6} \cdot (k_1 + 4 \cdot k_2 + k_3),$$

with

$$\begin{aligned}k_1 &= f(t, y), \\k_2 &= f\left(t + \frac{h}{2}, y + \frac{h}{2}k_1\right), \\k_3 &= f(t + h, y + h(-k_1 + 2k_2)).\end{aligned}$$

Show that the resulting one-step method is of consistency order  $p = 3$ . Which convergence order has the method?

## Exercise 2 (Integral Equation III and the classical RKM)

Consider the initial value problem (IVP) (see Exercise 1 on Sheet 1):

$$\begin{aligned} y'(t) &= f(t, y(t)), & t \in I := [0, T] \subset \mathbb{R}, \\ y(0) &= y_0 \end{aligned}$$

with  $f \in C^4(I \times \mathbb{R})$ . On Sheet 1, Exercise 1, we have already shown, that

$$y \text{ is solution of the IVP} \Leftrightarrow y(t) = Ky(t) := y_0 + \int_0^t f(s, y(s)) ds. \quad (2)$$

We discretize  $I$  equidistantly in  $N$  subintervals with stepsize  $h := \frac{T}{N} > 0$ , e.g.

$$0 = t_0 < t_1 < \dots < t_N = T$$

with  $t_k = k \cdot h$  for  $k = 0, 1, \dots, N$ . With (2) we obtain therefore

$$\frac{y(t_{k+1}) - y(t_k)}{h} = \frac{1}{h} \int_{t_k}^{t_{k+1}} f(s, y(s)) ds \quad \text{with} \quad y(t_0) = y_0. \quad (3)$$

(a) Derive the classical Runge-Kutta method by using (3) and

- using a quadrature formula (which one?) on  $\int_{t_k}^{t_{k+1}} f(s, y(s)) ds$ ,
- approximation of the function values of  $y$  by Taylor formula,
- elimination of the derivatives of  $y$ .

(b) Consider the IVP

$$\begin{aligned} y'(t) &= y(t), & t \in I := [0, T], \\ y(0) &= \alpha, \end{aligned}$$

with the exact solution  $y(t) = \alpha \cdot \exp t$ ,  $0 \leq t \leq T$ . Formulate for this IVP the classical Runge-Kutta method and discuss your observations.

## Exercise 3 (Explicit RKM)

Consider for  $I := [t_0, t_N] \subset \mathbb{R}$  the IVP

$$\begin{aligned} y'(t) &= f(t, y(t)), & t \in I, \\ y(t_0) &= y_0. \end{aligned}$$

(a) Consider the classical Runge-Kutta method with the Butcher-tableau:

0				
$\frac{1}{2}$	$\frac{1}{2}$			
$\frac{1}{2}$	0	$\frac{1}{2}$		
1	0	0	1	
	$\frac{1}{6}$	$\frac{1}{3}$	$\frac{1}{3}$	$\frac{1}{6}$

Which consistency order has the resulting explicit Runge-Kutta method and prove your statement.

(b) Write a function `y = runge_kutta_exp(f, tspan, y0, N)`, which runs the classical Runge-Kutta method with the Butcher-tableau given in (a). The time interval `tspan=[t0, tN]` shall be divided in  $N$  equidistant subintervals. `f` is a function handle.

(c) Apply the method on the following examples and vary  $N \in \{10, 50, 100, 500, 1000\}$

(i)  $u'(t) = -\lambda u(t)$ ,  $u(0) = 1$ , for  $\lambda \in \{-10, -1, 1, 10\}$  and  $t \in [0, 1]$ .

(ii)  $u'(t) = -t^2 u(t)^2$ ,  $u(0) = 1$ , for  $t \in [0, 1]$ .

(iii)  $u'(t) = -2tu(t)^2$ ,  $u(0) = 1$ , for  $t \in [0, 1]$ .

(iv) Davis-Skodje problem:

$$\begin{pmatrix} u'(t) \\ v'(t) \end{pmatrix} = \begin{pmatrix} -u(t) \\ -\frac{1}{\varepsilon}v(t) + \frac{u(t)}{\varepsilon(1+u(t))} - \frac{u(t)}{(1+u(t))^2} \end{pmatrix}$$

with the initial values

$$u(0) = 1 \quad \text{and} \quad v(0) = 1$$

for  $\varepsilon \in \{1, 10^{-1}, 10^{-2}, 10^{-3}, 10^{-4}, 10^{-6}\}$  and  $t \in [0, 4]$ .

(d) Apply further the explicit, implicit Euler method as well as the Crank-Nicolson method on the above examples with the same discretization. Discuss and explain your observations.

### Exercise 4 (Implicit RKM)

Consider for  $I := [t_0, t_N] \subset \mathbb{R}$  the IVP

$$y'(t) = f(t, y(t)), \quad t \in I,$$

$$y(t_0) = y_0.$$

(a) Consider two implicit Runge-Kutta methods, which are characterized by the following Butcher-tableaus:

$\alpha_1$	$\beta_{11}$	$\frac{3-2\sqrt{3}}{12}$	
$\frac{3+\sqrt{3}}{6}$	$\frac{3+2\sqrt{3}}{12}$	$\frac{1}{4}$	
	$\frac{1}{2}$	$\gamma_2$	

  

$\frac{5-\sqrt{15}}{10}$	$\frac{5}{36}$	$\frac{10-3\sqrt{15}}{45}$	$\frac{25-6\sqrt{15}}{180}$
$\frac{1}{2}$	$\frac{10+3\sqrt{15}}{72}$	$\frac{2}{9}$	$\frac{10-3\sqrt{15}}{72}$
$\frac{5+\sqrt{15}}{10}$	$\frac{25+6\sqrt{15}}{180}$	$\frac{10+3\sqrt{15}}{45}$	$\frac{5}{36}$
	$\frac{5}{18}$	$\frac{4}{9}$	$\frac{5}{18}$

Determine the coefficients  $\alpha_1, \beta_{11}$  and  $\gamma_2$  of the left Butcher-tableau, such that the resulting implicit Runge-Kutta method is of consistency order 4.

(b) Write a function `y = runge_kutta_imp(f, tspan, y0, N, alpha, gamma, A)`, with `tspan=[t0, tN]` which runs the implicit Runge-Kutta method with the Butcher-tableaus (described by `alpha, gamma, A`) given in (a). The time interval `tspan=[t0, tN]` shall be again divided in  $N$  equidistant subintervals. `f` is a function handle. Further, for solving the implicit system, use

(i) fixpoint iteration,

(ii) Newton method.

Compare and discuss the two methods.

(c) Apply the method on the Examples (i)-(iv) from Exercise 3 again with  $N \in \{10, 50, 100, 500, 1000\}$ .

### **Additional remarks to Exercise 3 and 4**

Create the plots in a meaningful manner! Make them as neat as possible! Plots without a title, without detailed description of the  $x$ - and  $y$ - axis or without a legend (if necessary) will not be accepted!

The following keywords could be useful:

- `doc figure`
- `doc plot`
- `doc subplot`
- `title`
- `xlabel, ylabel`
- `legend`
- `axis`