

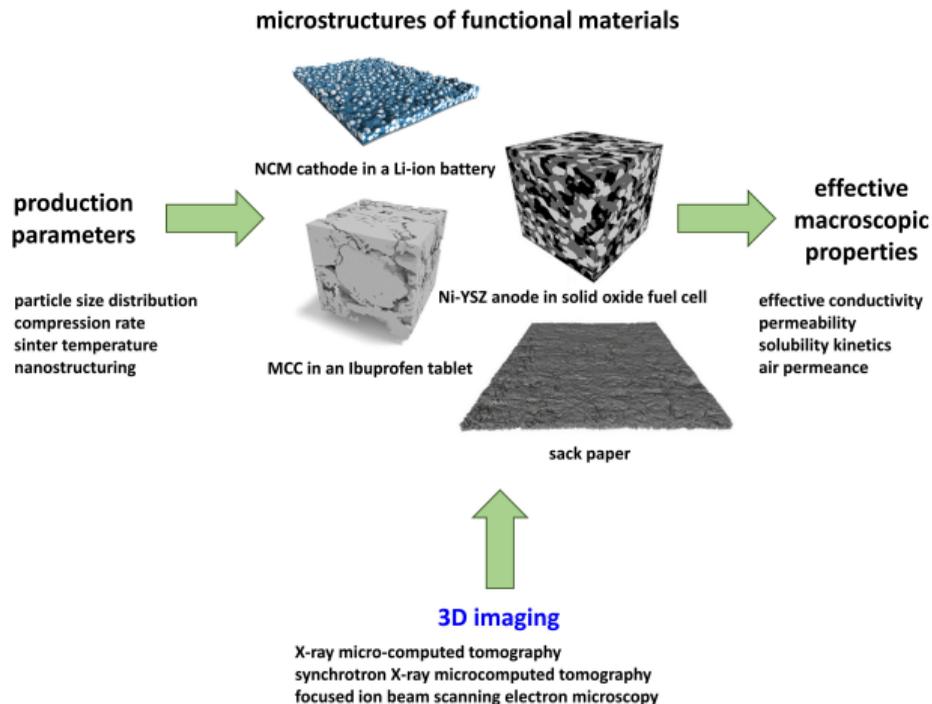
# Stochastic 3D modeling of the nanoporous binder-additive phase in battery electrodes

Matthias Neumann

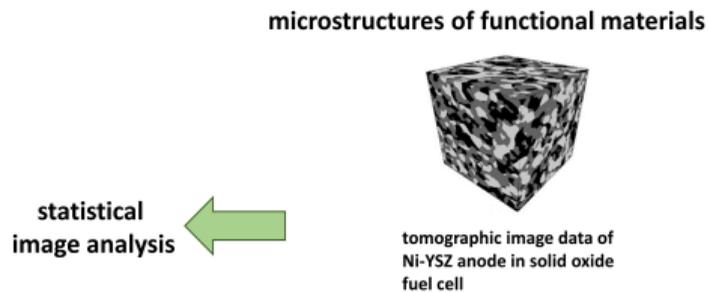
Joint work with Phillip Gräfensteiner and Volker Schmidt

September 24, 2024

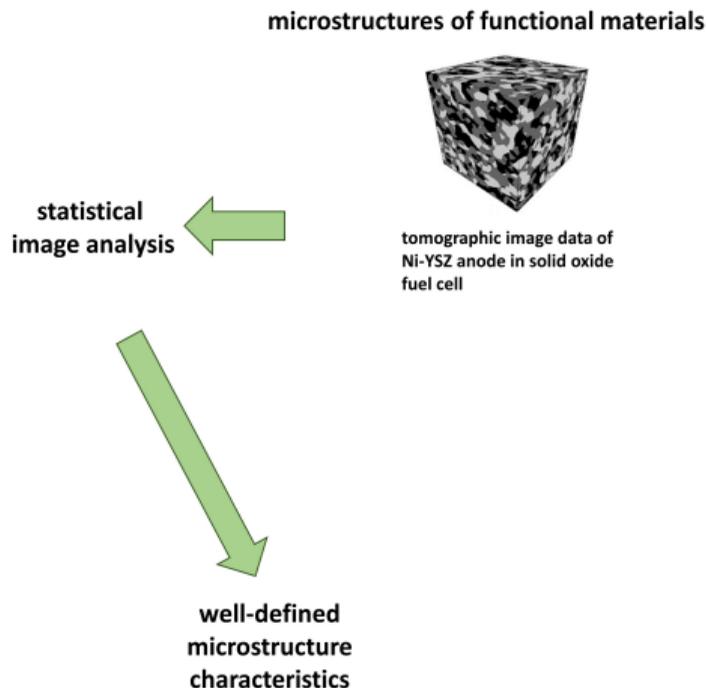
# Functional materials: Process-structure-property



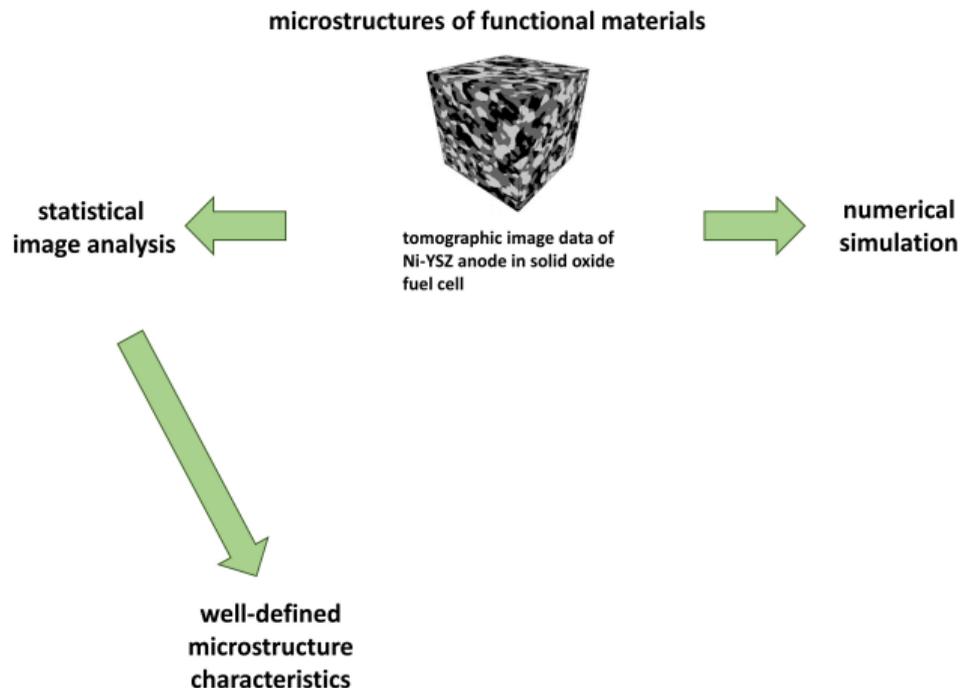
## Direct morphological approach



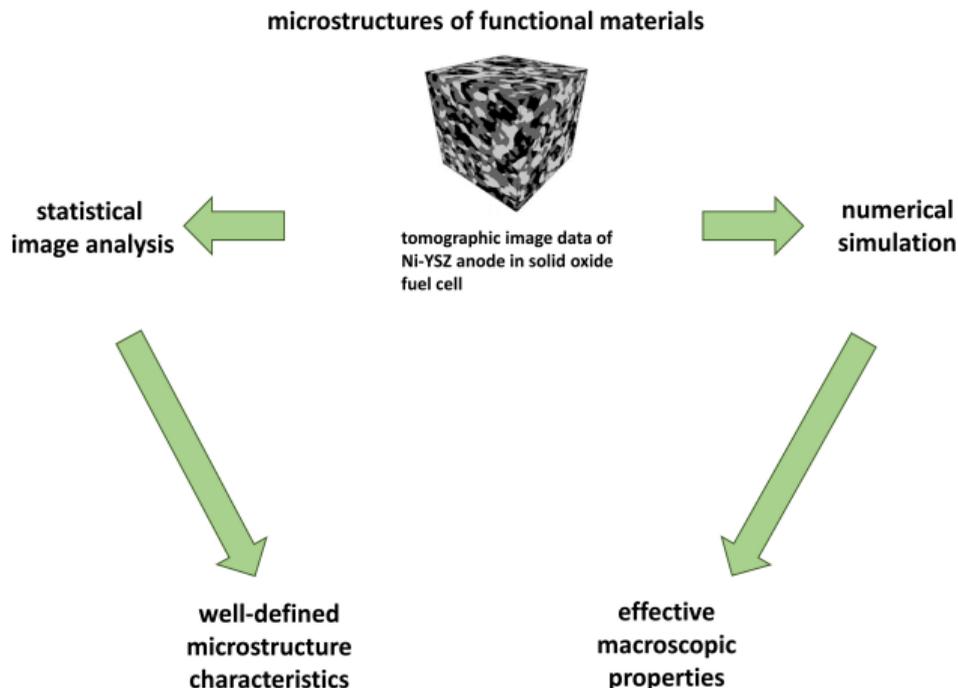
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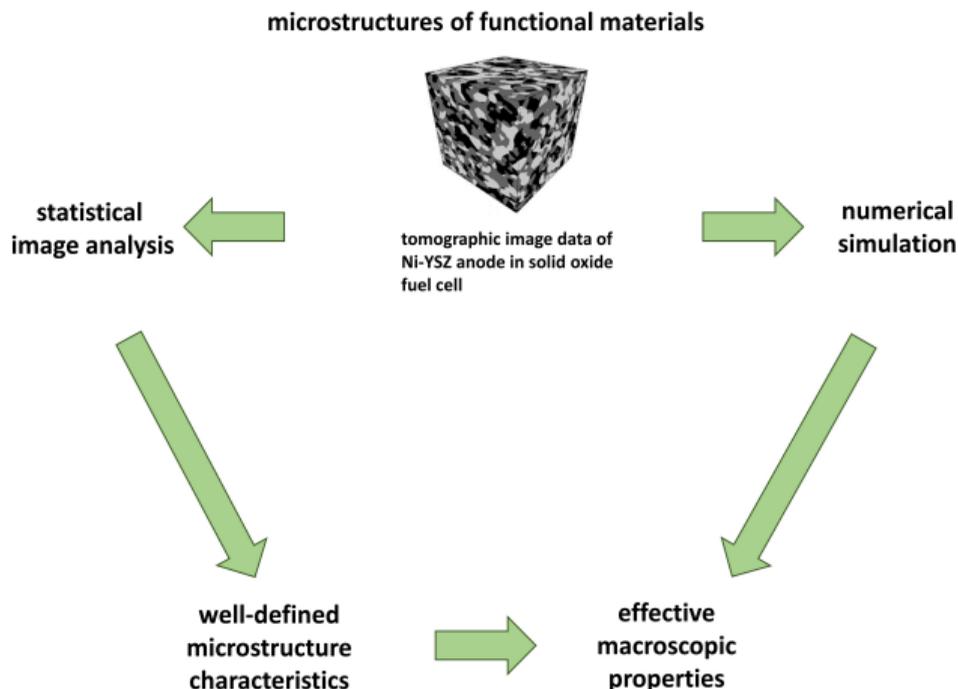
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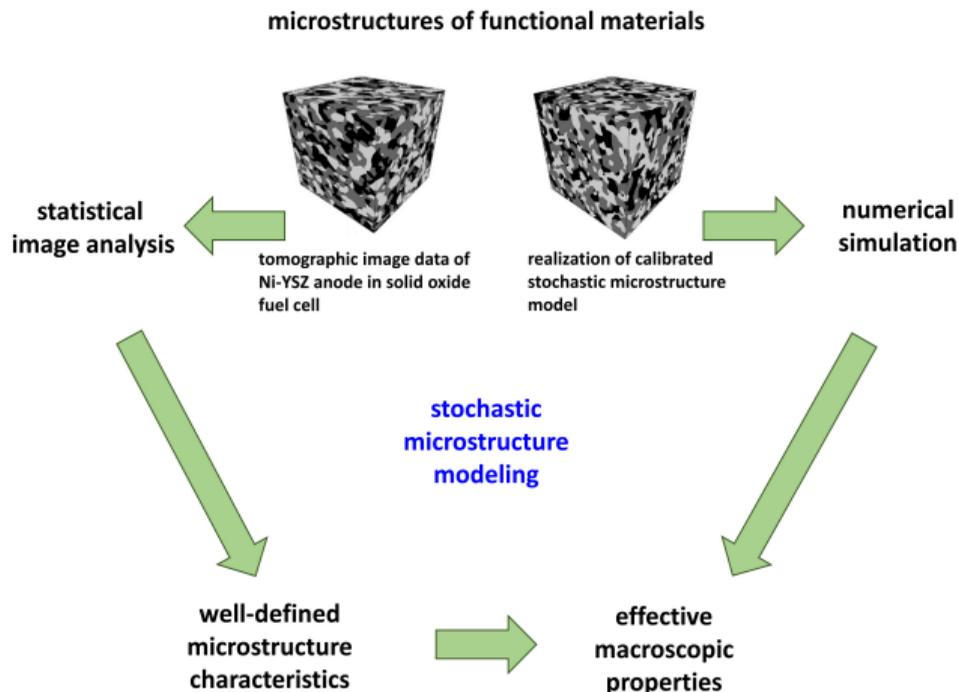
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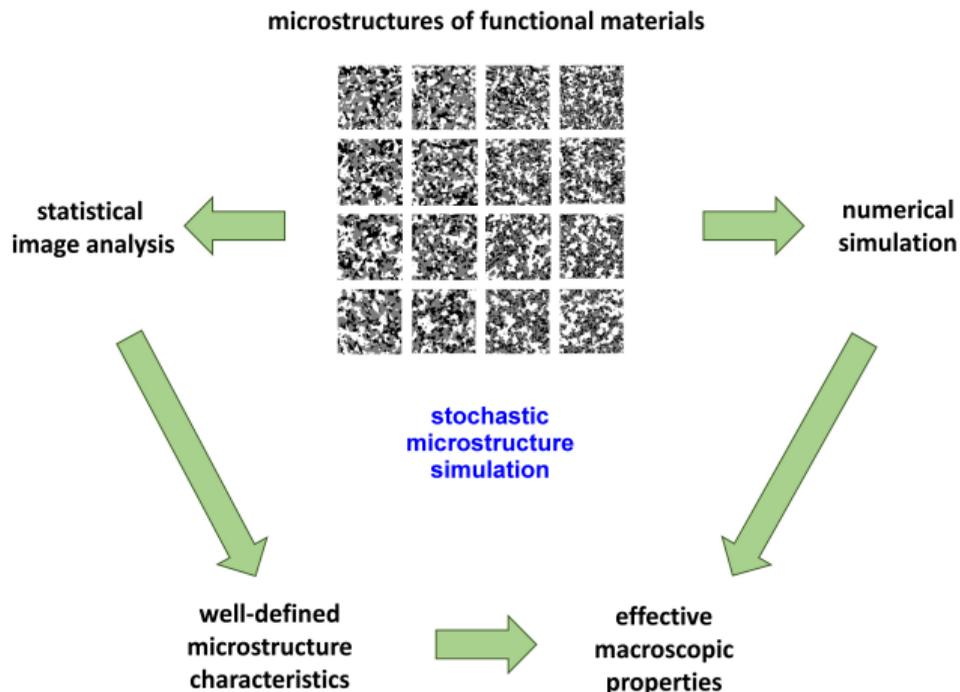
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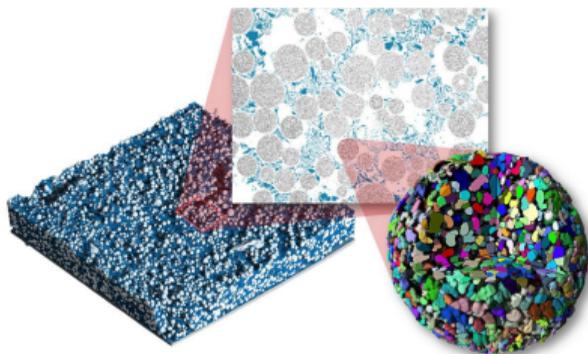
# Virtual materials testing



## Virtual materials testing



## Tomographic image data



Hierarchically structured  
NMC-cathode

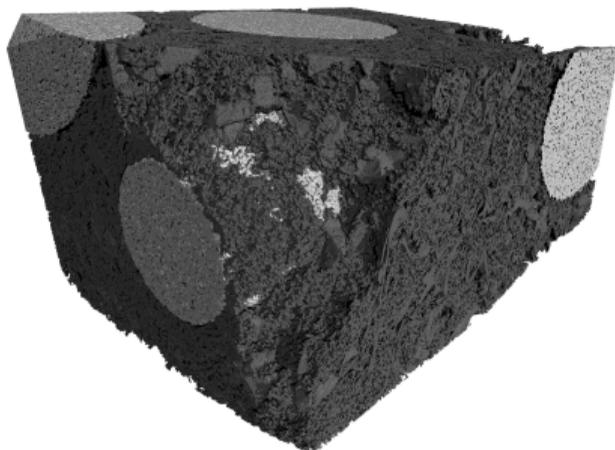
Wagner, Bohn, Geßwein, Neumann, Osenberg, Hilger, Manke, Schmidt, Binder. *ACS Appl. Energy Mater.* 3 (2020), 12565–12574.

Osenberg, Hilger, Neumann, Wagner, Bohn, Binder, Schmidt, Banhart, Manke. *J. Power Sources* 570 (2023), 233030.

Neumann, Wetterauer, Osenberg, Hilger, Gräfensteiner, Wagner, Bohn, Binder, Manke, Carraro, Schmidt. *Int. J. Solids Struct.* 280 (2023), 112394.

Neumann, Philipp, Neusser, Häringer, Binder, Kranz. *Batter. Supercaps* 7 (2024), 7:e202300409.

## Carbon binder domain surrounding active material

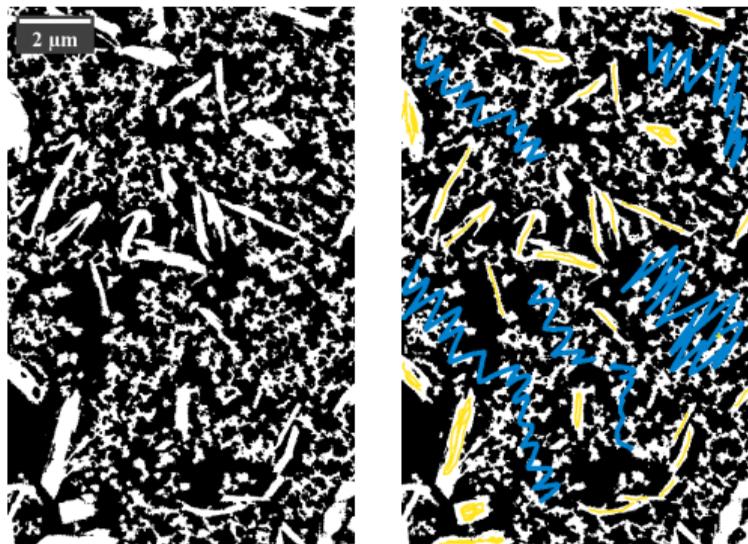


- Active material particles are embedded in a *nanoporous carbon binder domain*
- The nanostructure is resolved by *FIB-SEM tomography*
- Voxel size: 20 nm

Cadiou, Douillard, Willot, Badot, Lestriez, Maire. *J. Electrochem. Soc.* 167 (2020), 140504.

Kroll, Karstens, Cronau, Höltzel, Schlabach, Nobel, Redenbach, Ruling, Tallarek. *Batter. Supercaps* 4 (2021), 1363–1373.

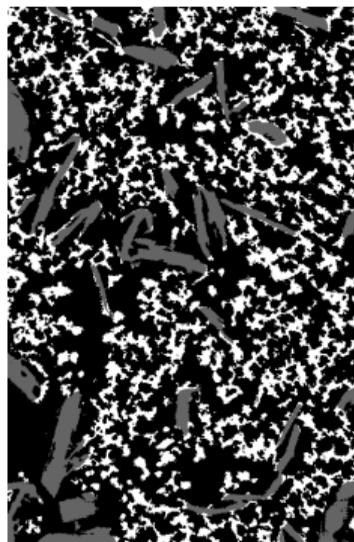
## Segmentation of graphite particles



- Large oblate-shaped objects represent *graphite* particles
- The finer structure represents *carbon black*
- Image segmentation performed by *Ilastik* using hand-labeled slices

Berg, Kutra, Kroeger, Straehle, Kausler, Haubold, Schiegg, Ales, Beier, Rudy, Eren, Cervantes, Xu, Beuttenmueller, Wolny, Zhang, Koethe, Hamprecht, Kreshuk. (2019). *Nature Methods*, 16:1226–1232.

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## Modeling idea

### Three-step approach

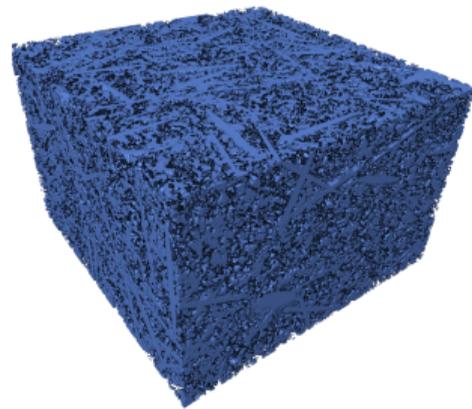
1. *Graphite particles* are modeled by a Boolean model, where the grains are given by oblate spheroids



## Modeling idea

### Three-step approach

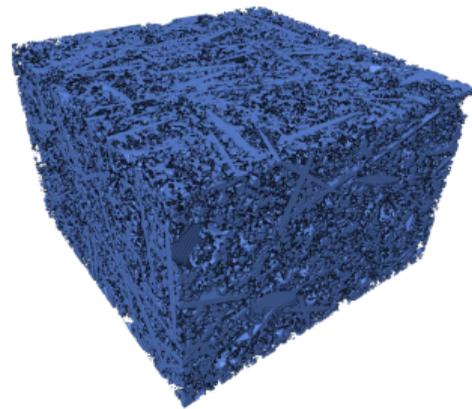
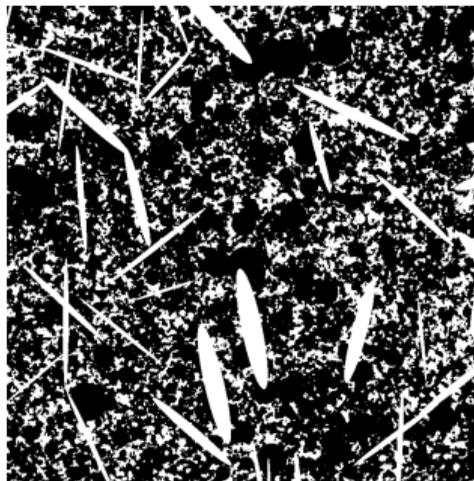
2. The union of *PVDF binder and carbon* is modeled by an excursion set of Gaussian random fields



## Modeling idea

### Three-step approach

3. *Large pore regions* are modeled by a second Boolean model with spherical grains



## Step 1: Graphite particles–model definition

### Boolean model with oblate spheroids as grains

- Let  $X_1, X_2, \dots$  be a homogeneous Poisson point process in  $\mathbb{R}^3$  with intensity  $\lambda_X > 0$ . Let  $E$  be a random oblate spheroid centered at the origin with random equatorial radius  $A$  and pole-to-centre distance  $C \leq A$ . Moreover, let the direction of the shorter semi-axis be uniformly distributed on the unit sphere.
- $A = \max\{W_1, W_2\}$  and  $C = \min\{W_1, W_2\}$ , where  $W_1, W_2$  are independent with  $W_1 \sim \Gamma(\alpha_1, \alpha_3)$ ,  $W_2 \sim \Gamma(\alpha_2, \alpha_3)$  for model parameters  $\alpha_1, \alpha_2, \alpha_3 > 0$ .
- For i.i.d copies  $E_1, E_2, \dots$  of  $E$ , define the union of graphite particles by  $\Xi_1 = \bigcup_{i=1}^{\infty} X_i + E_i$

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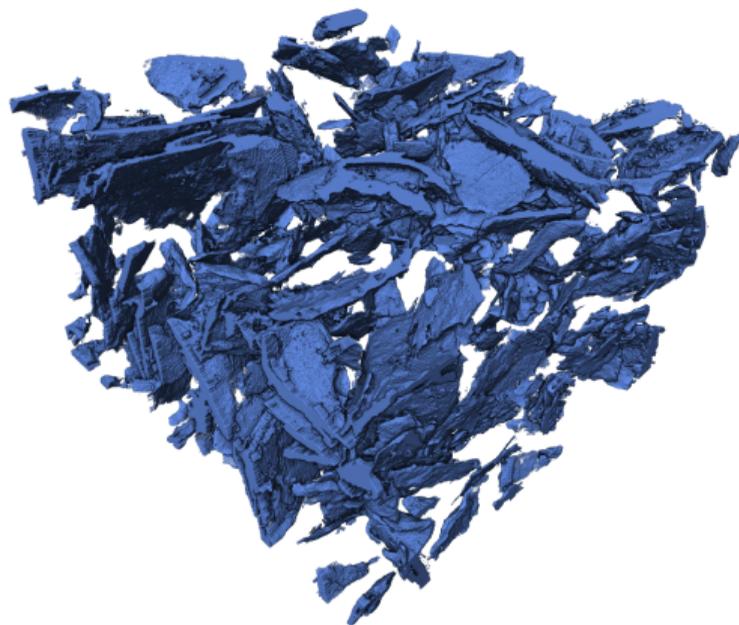
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Stochastic 3D modeling of the nanoporous binder-additive phase

## Step 1: Graphite particles—model fitting



Graphite particles extracted from image data

## Step 1: Graphite particles–model fitting

### Fit parameters $\lambda_X, \alpha_1, \alpha_2, \alpha_3$

- Fitting is based on volume fraction, surface area per unit volume, specific integral of mean curvature and the specific Euler number, which are estimated from image data.
- The above mentioned descriptors can be expressed as expectations of functions that depend on  $A$ ,  $C$ , and  $\lambda_X$  (Mile's formulae).
- Numerical fitting by the Nelder-Mead algorithm.

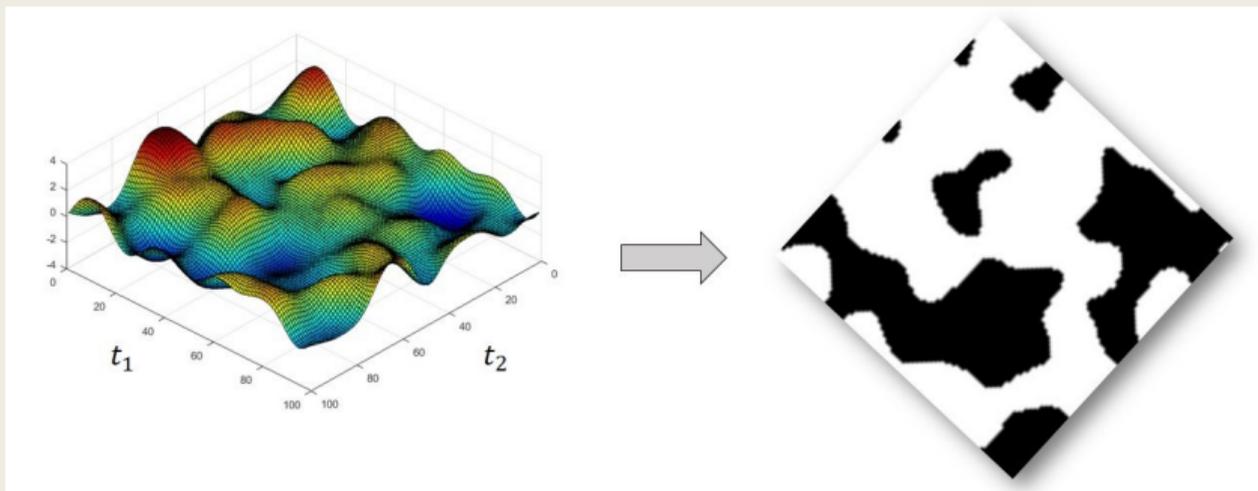
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## Step 2: PVdF binder and carbon-model definition

### Excursion set of a Gaussian random field



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### Excursion set of a Gaussian random field

- Let  $Z = \{Z(t) : t \in \mathbb{R}^3\}$  be a stationary and isotropic Gaussian random field with covariance function  $\rho$  such that  $\mathbb{E}[Z(t)] = 0$  and  $\text{Var}[Z(t)] = 1$  for each  $t \in \mathbb{R}^3$ .
- Define the union of PVdF binder and carbon by  $\Xi_2 \setminus \Xi_1$ , where  $\Xi_2 = \{t \in \mathbb{R}^3 : Z(t) \geq \mu\}$

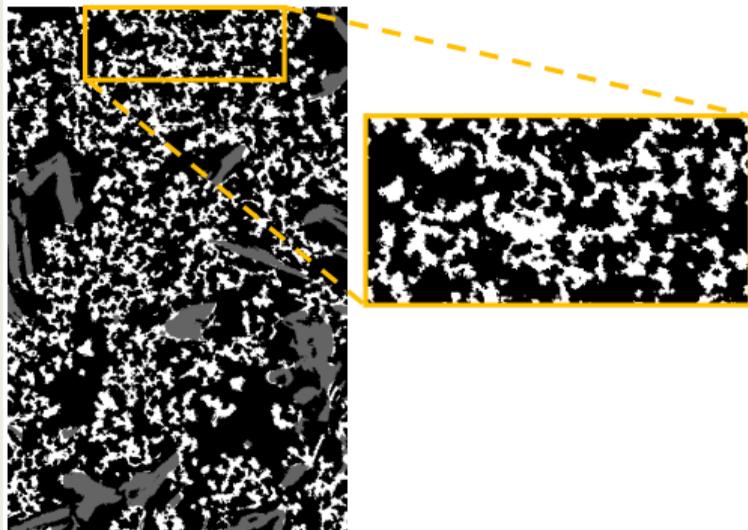
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## Step 2: PVdF binder and carbon-model fitting

Fitting the level  $\mu$  and the covariance function  $\rho$



Manually selected  
homogeneous cutout  
of PVdF binder and  
carbon

## Step 2: PVdF binder and carbon–model fitting

### Fitting the level $\mu$ and the covariance function $\rho$

- The level  $\mu$  is fitted such that the expected volume fraction in the model coincides with the volume fraction estimated from image data.
- For fitting  $\rho$ , we use

$$C(h) := P(s \in \Xi_2, t \in \Xi_2) = V_2^2 + \int_0^{\rho(h)} \frac{e^{-\frac{\mu^2}{1+t}}}{\sqrt{1-t^2}} dt,$$

for each  $h = |s - t|$ , where  $V_2$  is the volume fraction of  $\Xi_2$ .

## Step 2: PVdF binder and carbon–model fitting

### Fitting the level $\mu$ and the covariance function $\rho$

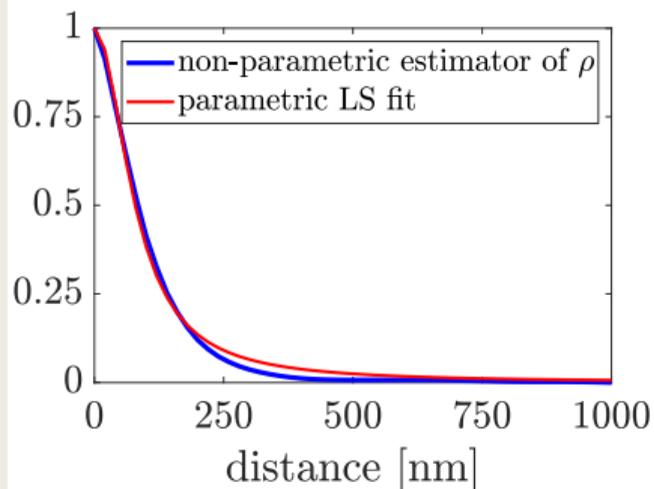
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## Step 2: PVdF binder and carbon-model fitting

### Fit of $\rho$



Consider the parametric family of covariance functions

$$\rho(h) = \frac{1}{1 + (\eta h)^2}$$

## Step 3: Large pore regions—model definition

### Boolean model with spherical grains

- Let  $Y_1, Y_2, \dots$  be a homogeneous Poisson point process in  $\mathbb{R}^3$  with intensity  $\lambda_Y > 0$ . Let  $R_1, R_2, \dots$  be i.i.d random variables with  $R_1 \sim \text{Exp}(\theta)$  for some  $\theta > 0$ .
- Define the union of large pore regions by  $\Xi_3 = \bigcup_{i=1}^{\infty} Y_i + b(o, R_i)$ , where  $b(o, r)$  is the open ball centered at the origin with radius  $r > 0$ .
- Model for the binder-additive phase (including graphite particles):

$$\Xi = \Xi_1 \cup (\Xi_2 \setminus \Xi_3).$$

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### Fitting $\lambda_Y$ and $\theta$

- For fixed  $\theta$ , we determine  $\lambda_Y$  such that the expected volume fraction of the model coincides with the value estimated from image data.
- Note that  $V = P(o \in \Xi) = P(o \in \Xi_1 \cup (\Xi_2 \cap \Xi_3^c)) = V_1 + V_2(1 - V_1)(1 - V_3)$  and

$$V_3 = 1 - \exp\left(\lambda_Y \frac{8\pi}{\theta^3}\right).$$

## Step 3: Large pore regions—model fitting

### Fitting $\lambda_V$ and $\theta$

- Based on simulated model realizations, the parameter  $\theta$  is determined in order to minimize the  $L_1$ -distance to the continuous pore size distribution estimated from image data.
- The continuous pore size distribution is defined as

$$\text{CPSD}(r) = \frac{\mathbb{E} \left[ \nu_3 \left( (\Xi^c \ominus B(o, r)) \oplus B(o, r) \right) \right]}{\mathbb{E}(\nu_3(\Xi^c))},$$

where  $B(o, r)$  denotes the closed ball centered at the origin with radius  $r > 0$ .

## Step 3: Large pore regions–model fitting

### Fitting $\lambda_V$ and $\theta$

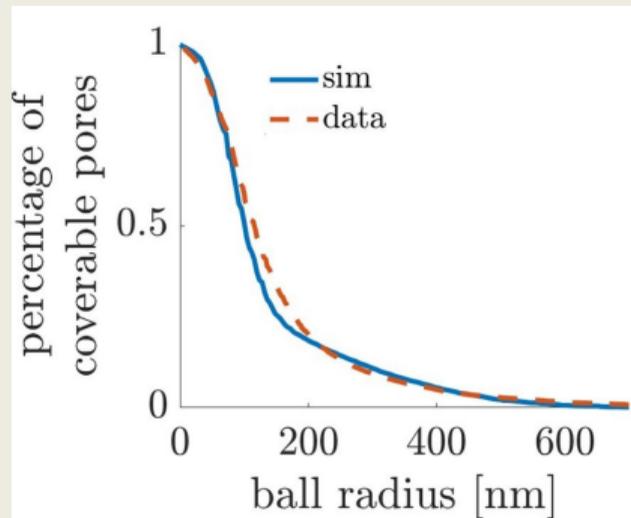
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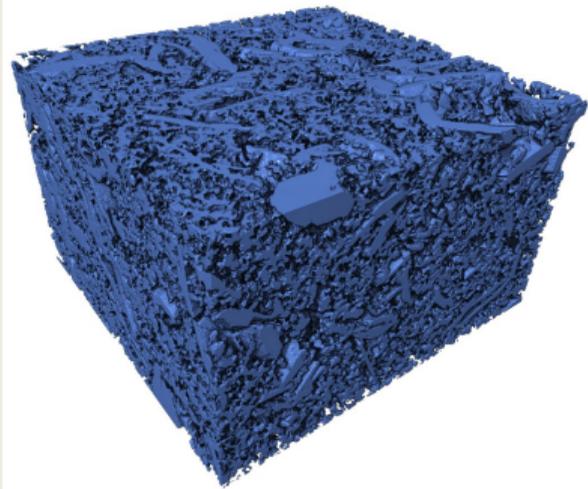
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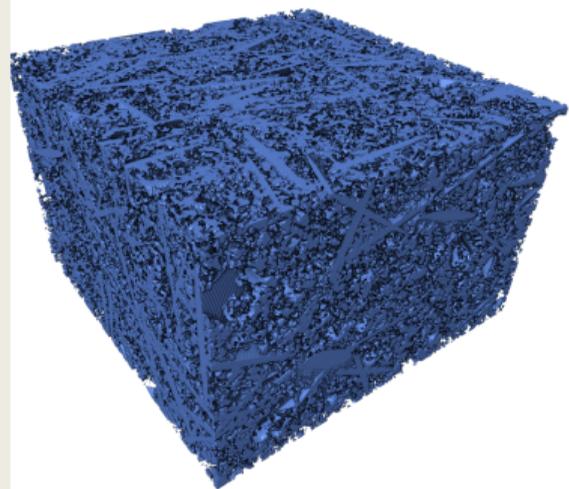


## Model validation

### Visual comparison



Data



Model realization

## Model validation

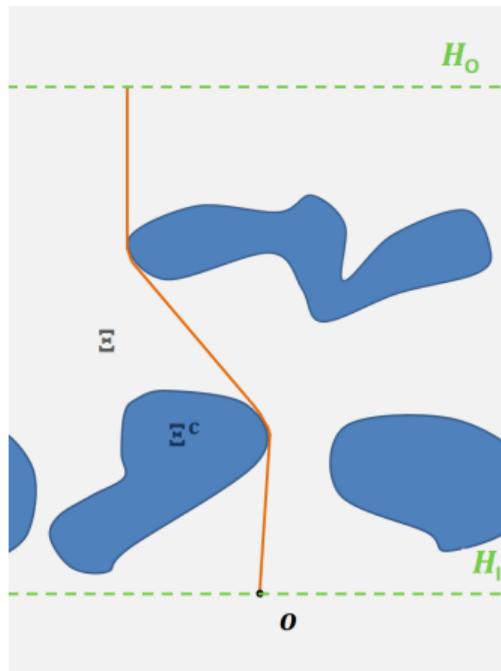
### Comparing morphological descriptors of measured and simulated nanostructures

- mean geodesic tortuosity  $\tau$  quantifying the length of shortest pathways
- constrictivity  $\beta$  measuring the degree of bottleneck effects
- Two-point coverage probability function  $C$  and specific surface area  $S$

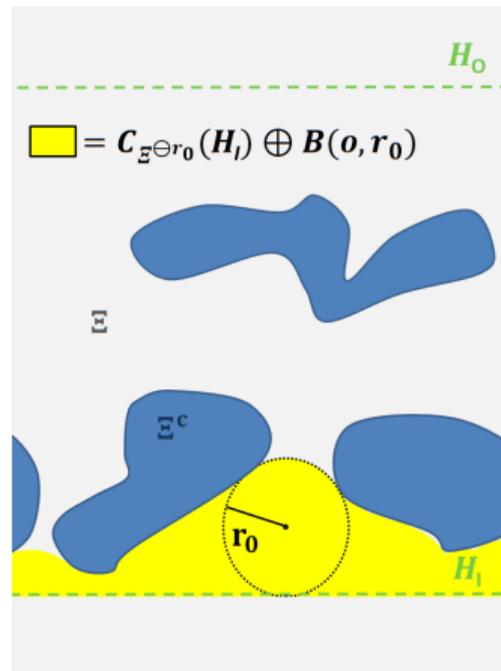
Peyrerga, Jeulin (2013). *Image Anal. Stereol.*, 32:27–43.

Neumann, Hirsch, Staněk, Beneš, Schmidt (2019). *Scand. J. Stat.*, 46:848–884.

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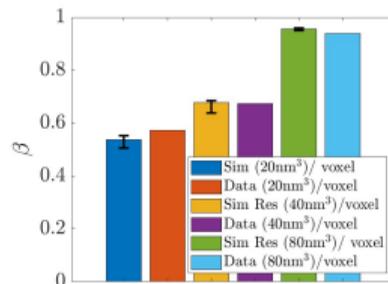
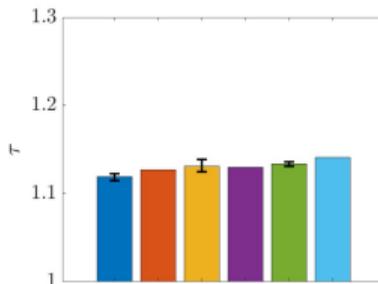
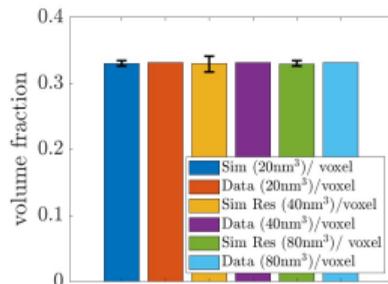


Mean geodesic tortuosity



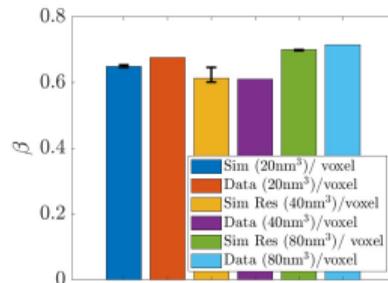
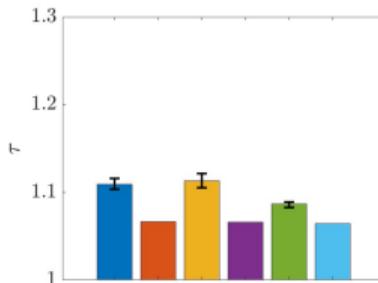
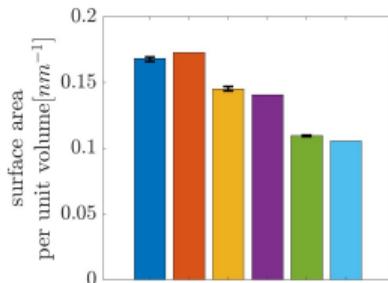
Constrictivity

## Model validation



solid phase

solid phase

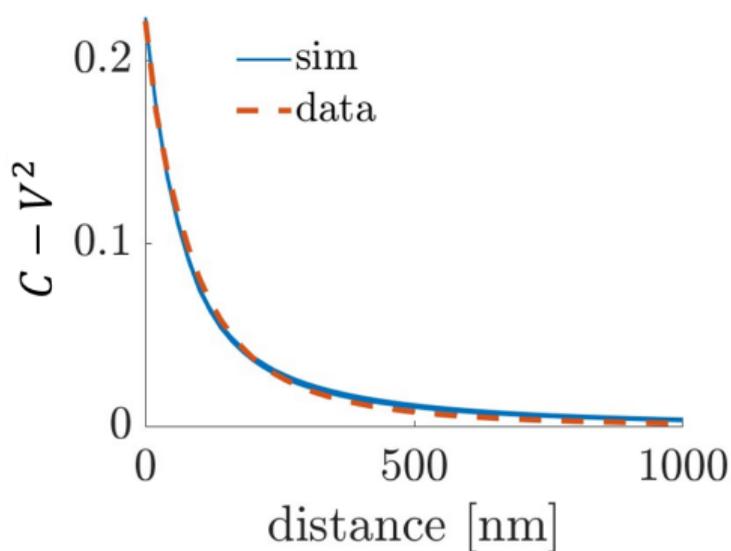


pore phase

pore phase

## Model validation

### Two-point coverage functions



$$C(h) = P(\mathbf{s} \in \Xi, \mathbf{t} \in \Xi), \\ |\mathbf{s} - \mathbf{t}| = h$$

## Effective properties

### M-factor

The  $M$ -factor is defined by

$$M = \sigma_{\text{eff}} / \sigma_0,$$

where  $\sigma_{\text{eff}}$  is the *effective* and  $\sigma_0$  is the *intrinsic conductivity (diffusivity)*.

- Here: *electric conduction* in the solid phase and *diffusion of ions* in the pore space.
- $M$ -factor is numerically simulated.

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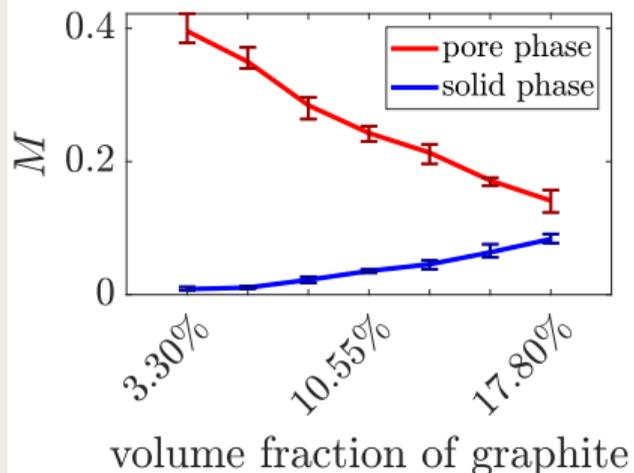
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## The role of graphite particles

### Simulation study



- The volume fraction of graphite particles is varied by varying  $\lambda_X$ .
- All other model parameters remain unchanged.

## Conclusions

- A stochastic 3D model has been developed for the carbon binder domain in lithium-ion battery electrodes.
- Boolean models have been combined with excursion sets of Gaussian random fields.
- Model fitting is performed based on segmented 3D image data.
- The validated model is used to study the influence of the amount of graphite particles on effective properties.

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