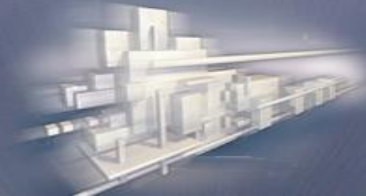




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Weak Convergence in Metric Spaces

Shiyuan Fan | 25. May 2010

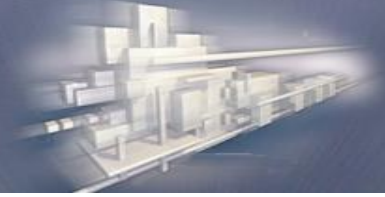


- In measure theory, there are various notions of the convergence of measures. Broadly speaking, there are two kinds of convergence, strong convergence and weak convergence.
- **strong convergence:** If the collection of all measures on a measurable space can be given some kind of metric, then convergence in this metric is usually referred to as strong convergence.
- **weak convergence:**

S metric space \mathcal{P} class of Borel sets in S P probability measure on \mathcal{P}

If $\int_S f dP_n \rightarrow \int_S f dP$ for every bounded, continuous real function f on S , we write $P_n \Rightarrow P$





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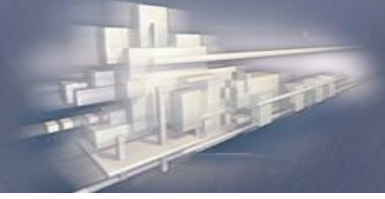
Applications

The Central Limit Theorem

DeMoivre-Laplace Theorem

Proposition of Slutsky





Measures and Integrals

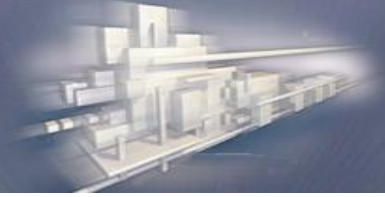
- Every probability measure on (S, \mathcal{F}) is regular; that is, if $A \in \mathcal{F}$ and $\varepsilon > 0$, then there exist a closed set F and an open set G such that $F \subset A \subset G$ and $P(G - F) < \varepsilon$.

- Probability measures P and Q on (S, \mathcal{F}) coincide if

$$\int f dP = \int f dQ \quad \text{for each } f \text{ in } C(S).$$

- If F is closed and ε positive, there is a function f in $C(S)$ s.t.
 $f(x) = 1$ if $x \in F$, $f(x) = 0$ if $\rho(x, F) \geq \varepsilon$, and $0 \leq f(x) \leq 1$ for all x .
The function f may be taken to be uniformly continuous.





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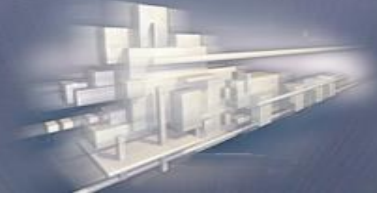
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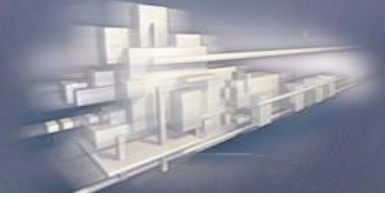


Portmanteau Theorem

Let P_n, P be probability measures on (S, \mathcal{F}) . These five conditions are equivalent:

- (i) $P_n \Rightarrow P$.
- (ii) $\lim_n \int f dP_n = \int f dP$ for all bounded, uniformly continuous real f .
- (iii) $\limsup_n P_n(F) \leq P(F)$ for all closed F .
- (iv) $\liminf_n P_n(G) \geq P(G)$ for all open G .
- (v) $\lim_n P_n(A) = P(A)$ for all P -continuity sets A .





Other Criteria

- Let \mathcal{U} be a class of sets s.t.
 - (i) \mathcal{U} is closed under the formation of finite intersections;
 - (ii) each open set in S is a finite or countable union of elements of \mathcal{U}If $P_n(A) \rightarrow P(A)$ for every A in \mathcal{U} , then $P_n \Rightarrow P$.

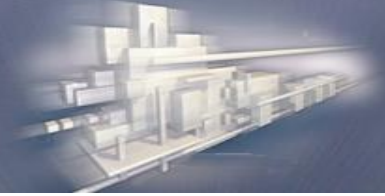
- Corollary:

Let \mathcal{U} be a class of sets s.t.

- (i) \mathcal{U} is closed under the formation of finite intersections;
- (ii) for every x in S and every positive ε there is an A in \mathcal{U} with
$$x \in \text{int}(A) \subset A \subset S(x, \varepsilon).$$

If S is separable and if $P_n(A) \rightarrow P(A)$ for every A in \mathcal{U} , then $P_n \Rightarrow P$.





Other Criteria

- Corollary:

Suppose that, for each finite intersection A of open spheres, we have

$P_n(A) \rightarrow P(A)$, provided A is a P -continuity set. If S is separable, then

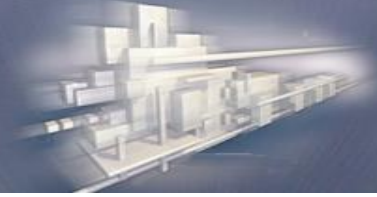
$P_n \Rightarrow P$.

- Another condition for weak convergence:

We have $P_n \Rightarrow P$ if and only if each subsequence $\{P_{n'}\}$ contains a

further subsequence $\{P_{n''}\}$ s.t. $P_{n''} \Rightarrow P$.





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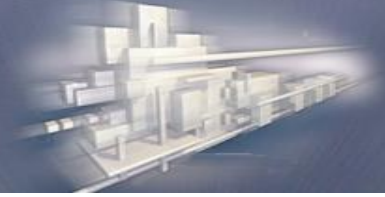
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Euclidean Space

- We can relate weak convergence $P_n \Rightarrow P$ to the usual notion of convergence for the corresponding distribution functions F_n, F .

- R^K k-dimensional Euclidean space

$\rho(x, y)$ ordinary metric which equals $|x - y| = \sqrt{\sum_{i=1}^k (x_i - y_i)^2}$

\mathcal{R}^K the class of Borel sets

- The general probability measure P on (R^K, \mathcal{R}^K) has a distribution function F :

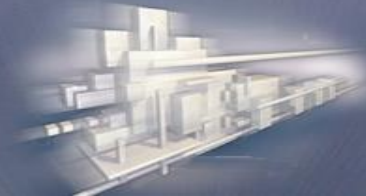
$$F(x) = P\{y : y \leq x\}, x \in R^K.$$

- For distribution functions F_n and F , define $F_n \Rightarrow F$ to mean that

$F_n(x) \rightarrow F(x)$ at continuity points x of F .

- We can prove that if $P_n \Rightarrow P$, then $F_n \Rightarrow F$

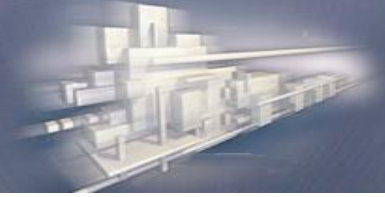




The Circle

- S is the unit circle in the complex plane.
- $P_n \Rightarrow P$ if and only if $P_n(A) \rightarrow P(A)$ for every arc A whose endpoints have P -measure 0.





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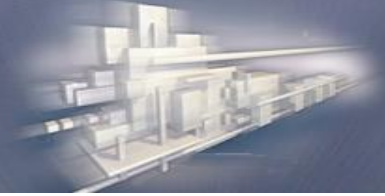
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Random Elements

- X is a mapping from a probability space $(\Omega, \mathcal{B}, \mathbf{P})$ into a metric space S .
If X is measurable, we call it a random element.

- The distribution of X is the probability measure P on (S, \mathcal{F}) :

$$P(A) = \mathbf{P}(X^{-1}A) = \mathbf{P}(\omega : X(\omega) \in A) = \mathbf{P}(X \in A)$$

- Note that \mathbf{P} is a probability measure on a space of an arbitrary nature, whereas P is always defined on a metric space. For many questions, the distribution P contains all relevant information about the random element X .

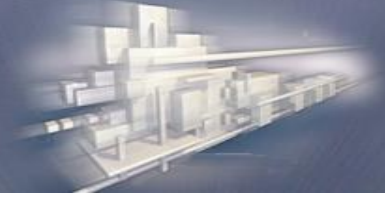
- If h is a measurable function on S , then by change-of-variable formula

$$\int h(X) d\mathbf{P} = \int h dP$$

In the usual expected-value notation,

$$\int h dP = \mathbf{E}[h(X)]$$

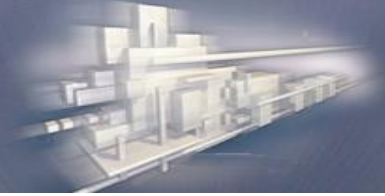




Convergence in Distribution

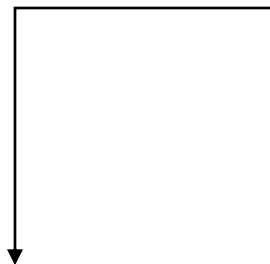
- A sequence $\{X_n\}$ of random elements converges in distribution to the random element X : $X_n \xrightarrow{\mathcal{D}} X$, if the distributions P_n of the X_n converge weakly to the distribution P of X : $P_n \Rightarrow P$.
- The underlying probability spaces (the domains) may be all distinct.
- Each theorem about weak convergence can be similarly recast.





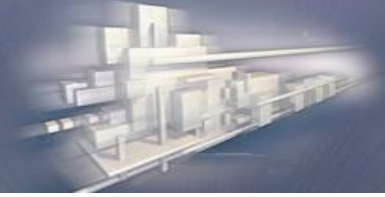
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- (i) $P_n \Rightarrow P$.
- (ii) $\lim_n \int f dP_n = \int f dP$ for all bounded, uniformly continuous real f .
- (iii) $\limsup_n P_n(F) \leq P(F)$ for all closed F .
- (iv) $\liminf_n P_n(G) \geq P(G)$ for all open G .
- (v) $\lim_n P_n(A) = P(A)$ for all P -continuity sets A .



- (i) $X_n \xrightarrow{\mathcal{D}} X$
- (ii) $\lim_n E[f(X_n)] = E[f(X)]$ for all bounded, uniformly continuous real f .
- (iii) $\limsup_n P(X_n \in F) \leq P(X \in F)$ for all closed F .
- (iv) $\liminf_n P(X_n \in G) \geq P(X \in G)$ for all open G .
- (v) $\lim_n P(X_n \in A) = P(X \in A)$ for all X -continuity sets A .





Convergence in Distribution

- Hybrid terminology:

We say the X_n converge in distribution to P , and write

$$X_n \xrightarrow{\mathcal{D}} P,$$

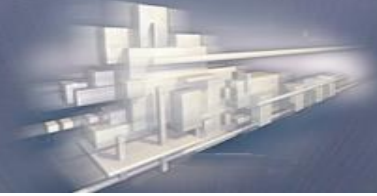
in case $P_n \Rightarrow P$.

- It is great convenience to be able to pass from one to another of three equivalent concepts. This is largely a matter of expedient phraseology.

- Example:

$$X_n \xrightarrow{\mathcal{D}} N(\mu, \sigma^2).$$





Convergence in Probability

- If, for an element a of S ,

$$P\{\rho(X_n, a) \geq \varepsilon\} \rightarrow 0$$

for each positive ε , we say X_n converges in probability to a and write

$$X_n \xrightarrow{\mathcal{P}} a.$$

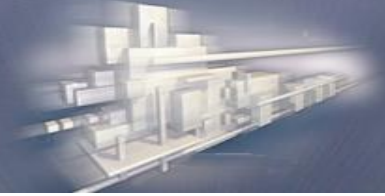
- If a is conceived as a constant-valued random element, then

$$X_n \xrightarrow{\mathcal{P}} a \text{ if and only if } X_n \xrightarrow{\mathcal{D}} a \quad .$$

- Alternatively, $X_n \xrightarrow{\mathcal{P}} a$ if and only if the distribution of X_n

converges weakly to the probability measure corresponding to a mass of 1 at the point a .





Convergence in Probability

- If, for an element a of S ,

$$P\{\rho(X_n, a) \geq \varepsilon\} \rightarrow 0$$

for each positive ε , we say X_n converges in probability to a and write

$$X_n \xrightarrow{\mathcal{P}} a.$$

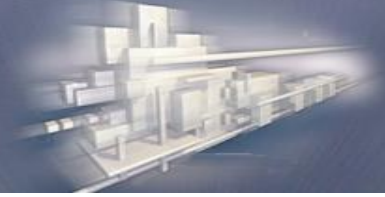
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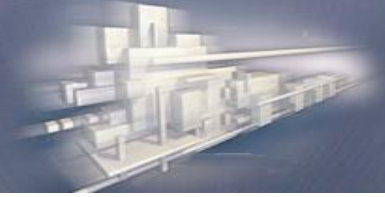
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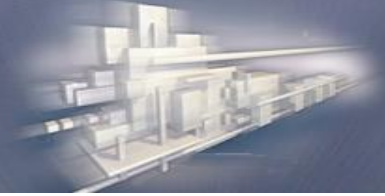




Continuous Mappings

- h is a measurable mapping $: S \rightarrow S'$, then each probability measure P on (S, \mathcal{F}) induces on (S', \mathcal{F}') a unique probability measure Ph^{-1}
- $Ph^{-1}(A) = P(h^{-1}A), A \in \mathcal{F}'$
- If h is a continuous mapping, $P_n \Rightarrow P$ implies $P_n h^{-1} \Rightarrow Ph^{-1}$.

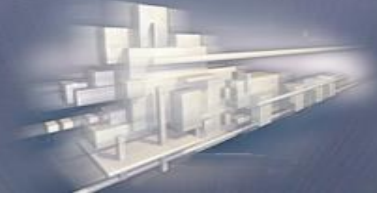




Main Theorem

- We can weaken the continuity assumption of h .
- Assume only h is measurable and let D_h be the set of discontinuities of h . Then we can prove $D_h \in \mathcal{G}$.
- If $P_n \Rightarrow P$ and $P(D_h) = 0$, then $P_n h^{-1} \Rightarrow P h^{-1}$.





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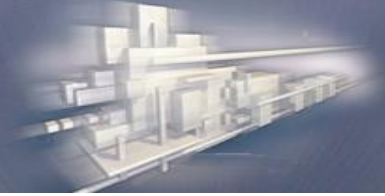
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- $\xi_{n1}, \dots, \xi_{nk_n}$ are independent random variables with mean 0 and finite variance σ_{nk}^2 . The probability space on which the variables are defined may vary with n.
- $S_n = \xi_{n1} + \dots + \xi_{nk_n}$ and suppose its variance $s_n^2 = \sigma_{n1}^2 + \dots + \sigma_{nk_n}^2$ is positive.
- N is a random variable normally distributed with mean 0 and variance 1.
- Lindeberg's theorem:

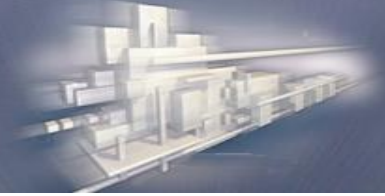
If

$$\frac{1}{s_n^2} \sum_{k=1}^{k_n} \int_{\{|\xi_{nk}| \geq \varepsilon s_n\}} \xi_{nk}^2 dP \rightarrow 0 (n \rightarrow \infty)$$

for each positive ε , then

$$\frac{S_n}{s_n} \xrightarrow{\mathcal{D}} N.$$





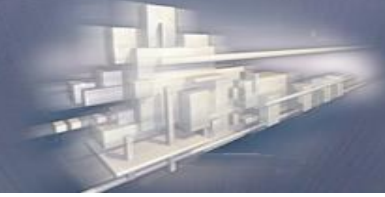
- From the last theorem we can deduce the lindeberg-Levy theorem:

If ξ_1, ξ_2, \dots are independent and identical distributed with mean 0 and finite variance $\sigma^2 > 0$, then

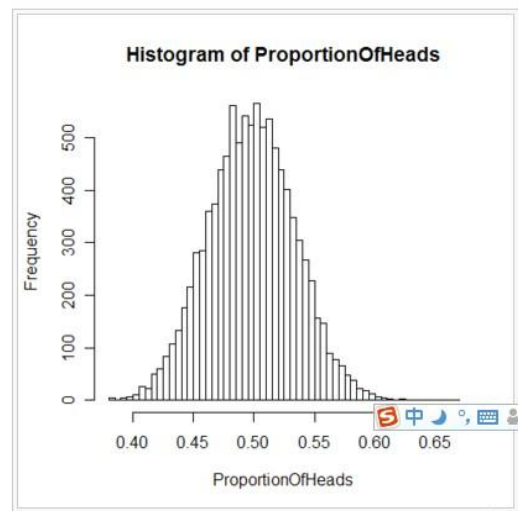
$$\frac{1}{\sigma\sqrt{n}} \sum_{k=1}^n \xi_k \xrightarrow{\mathcal{D}} N.$$

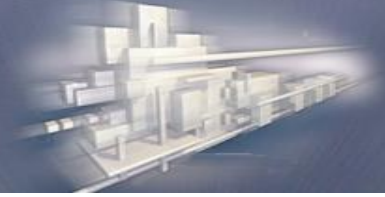
- To prove this result, take $k_n = n, \xi_{ni} = \xi_i$; the sum in former equation is at most ξ_1^2 / σ^2 integrated over $\{|\xi_1| \geq \varepsilon\sigma\sqrt{n}\}$.





- A **central limit theorem** is any of a set of weak-convergence theories. They all express the fact that a sum of many independent random variables will tend to be distributed according to one of a small set of "attractor" (i.e. stable) distributions.
- the central limit theorem states conditions under which the mean of a sufficiently large number of independent random variables, each with finite mean and variance, will be approximately normally distributed





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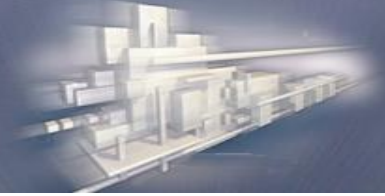
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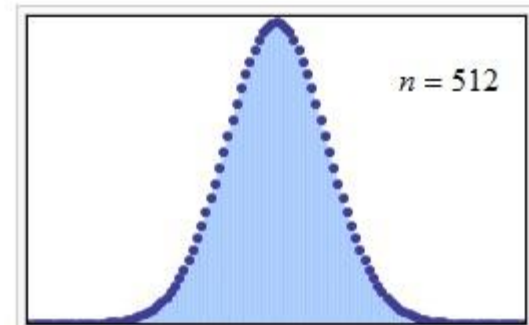
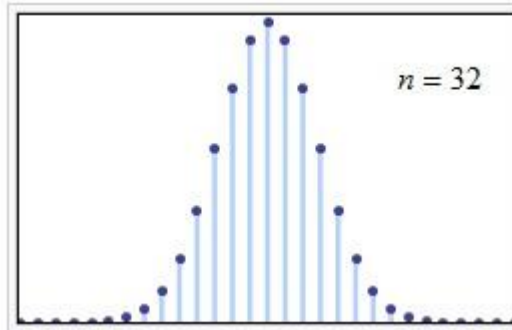
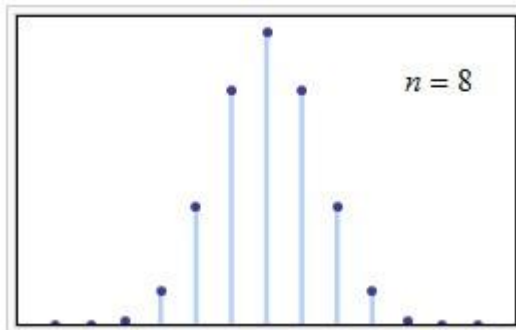
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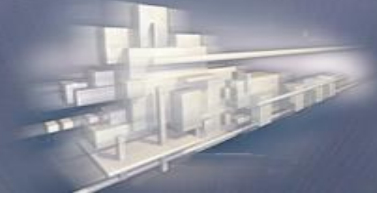
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- The **de Moivre–Laplace theorem** is a normal approximation to the binomial distribution. It is a special case of the central limit theorem. It states that the binomial distribution of the number of "successes" in n independent trials with probability p of success on each trial is approximately a normal distribution with mean np and standard deviation $\sqrt{np(1-p)}$, if n is very large and some conditions are satisfied.





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Given $X_n \xrightarrow{\mathcal{D}} X, Y_n \xrightarrow{\mathcal{P}} c$, where c is a constant, then

$$X_n + Y_n \xrightarrow{\mathcal{D}} X + c;$$

$$X_n Y_n \xrightarrow{\mathcal{D}} cX;$$

$$Y_n^{-1} X_n \xrightarrow{\mathcal{D}} c^{-1} X.$$

The theorem remains valid if we replace all convergences in distribution with convergences in probability





Thank You!