Discounted Stochastic Games with Voluntary Transfers

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Discounted Stochastic Games

Natural generalization of infinitely repeated games

- n players
- ullet infinitely many periods, common discount factor $\delta < 1$
- in every period there is a state $x \in X$ (finite)
- Stage game
 - actions $a = (a_1, ..., a_n) \in A(x)$
 - payoffs $\pi(a,x)$
- State can change after every period
 - $\tau(x'|x,a)$: probability that new state is x'
- This talk: Players publicly observe a and x (perfect monitoring)

Example: Cournot Model with Stochastic Reserves

- Two firms i = 1, 2 that operate hydro-electric power plants
- State $x = (x_1, x_2) \in \{0, 1, ..., \bar{x}\}^2$ amount of hydro-energy in each firm's water reservoir
- Firma *i* can sell in a period $a_i \in \{0, 1, ..., x_i\}$ units of energy.
- Stage game profits:

$$\pi_i(a,x) = P(a_1,a_2)a_i$$

• New state depends on random rainfall:

$$x_i' = x_i - a_i + \varepsilon_i$$

Solving stochastic games... for Markov perfect equilibria?

- Most applied literature: Markov perfect equilibria (MPE)
 - actions depend only on current state x

Problems with MPE

- Multiple MPE can exist (e.g. Besanko et. al., 2010)
- Set of MPE payoffs often unknown
- Set of MPE payoffs can be very sensitive to state space
 - single state (infinitely repeated game):
 MPE = repetition of static Nash equilibrium
 - including (almost) payoff irrelevant states, e.g. output in previous period, may allow quite collusive MPE

Solving stochastic games... for subgame perfect equilibria?

- Set of SPE payoffs hard to characterize
- Large discount factors $(\delta
 ightarrow 1)$ & irreducible stochastic game
 - Dutta (1995), Hörner et. al. (2011)
- Fixed δ : Extending algorithms for repeated games?
 - Abreu, Pearce and Stachetti (1990), Judd, Yeltekin, Conklin (2003), Abreu & Sannikov (2011)
- Pareto-optimal equilibria don't have in general a simple structure

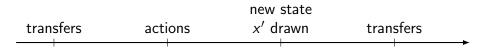
This paper

- Considers an economic relevant subset of stochastic games
- Main results:
 - every SPE payoff can be implemented with a simple class of equilibria
 - methods to analytically find or to compute equilibrium payoff sets

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- Considers an economic relevant subset of stochastic games
- Main results:
 - every SPE payoff can be implemented with a simple class of equilibria
 - methods to analytically find or to compute equilibrium payoff sets
- Stochastic games with voluntary monetary transfers and risk-neutral players
 - repeated games: Levin (2003), Goldluecke und Kranz (2010), Malcomson & McLeod (1989), Doornik (2006), Rayo (2007), Klimenko, Ramey and Watson (2008), Harrington and Skrzypacz (2007),...
 - transfers implemented in several cartels via sales between firms

Structure of a period in game with transfers



- Transfers: players chooses simultaneously amount of money they want to transfer to other players
 - no binding liquidity constraints
 - money burning possible
 - received net amount of money will be added to payoffs $\pi_i(a,x)$

Simple strategy profiles

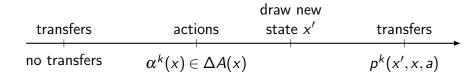
Basic structure

- n+1 phases $k \in \{e, 1, ..., n\}$
 - equilibrium phase k = e
 - a punishment phase k = i

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Simple strategy profiles

Play in phase k state x



exception: upfront transfers in first period

Simple strategy profiles

Transition between phases

- phase only changes after upfront transfer or after transfer at end of period
 - ▶ player *i* unilaterally deviates from his transfer ⇒punishment phase *k* = *i*
 - no player unilaterally deviates from transfer \Rightarrow equilibrium phase k = e
- punishment have a stick-and-carrot structure (similar to Abreu, 1986)

Main Result

Theorem

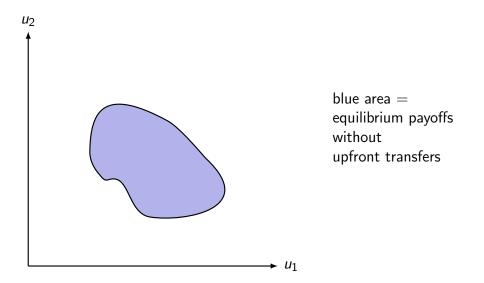
Fix a discount factor δ : Every SPE payoff can be implemented with an equilibrium in simple strategies.

Intuition

Incentive compatible monetary transfers can be used for three important functions

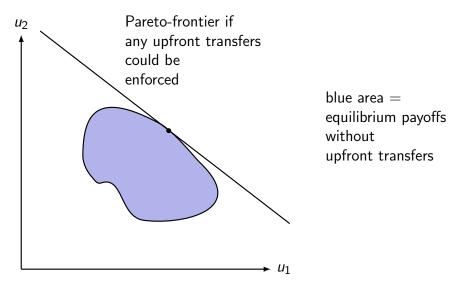
Distribute joint payoffs (with upfront payments)

- Balance incentive constraints between players
- Fines as punishment

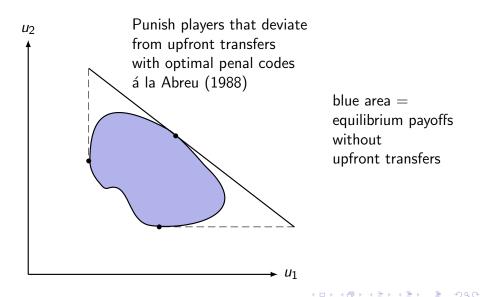


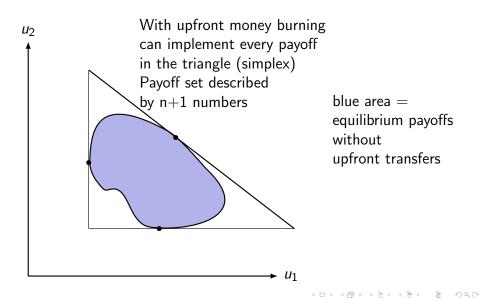
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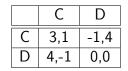
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2. Balancing incentive constraints

- Repeated asymmetric Prisoners' dilemma
- Aim: (C,C) in every period
- Punishment: (D,D) forever



• Incentive constraints for subgame perfection

$$\begin{array}{ll} \mathsf{Player 1:} & \sum_{t=0}^{\infty} 3\delta^t = \frac{3}{1-\delta} \geq 4 \Leftrightarrow \delta \geq \frac{1}{4} \\ \mathsf{Player 2:} & \sum_{t=0}^{\infty} \delta^t = \frac{1}{1-\delta} \geq 4 \Leftrightarrow \delta \geq \frac{3}{4} \end{array}$$

 Given asymmetries stationary equilibrium play may not be optimal (without transfers)

2. Balancing incentive constraints

• Assume pl. 1 transfers 1 unit of money every period on eq. path to pl. 2. No incentives to deviate from (*C*, *C*):

Player 1:
$$\frac{3-1}{1-\delta} \ge 4 \Leftrightarrow \delta \ge \frac{1}{2}$$

Player 2: $\frac{1+1}{1-\delta} \ge 4 \Leftrightarrow \delta \ge \frac{1}{2}$

• Consider summed incentive constraints:

$$\frac{3\!+\!1}{1\!-\!\delta} \geq 4\!+\!4 \Leftrightarrow \delta \geq \frac{1}{2}$$

• General result: if summed incentive constraints hold, one can always find transfers such that no player has incentives to deviate from individual actions or transfers

3. Fines as punishment

- Allow a player who deviates to avoid punishment actions by paying a fine
- Punishment actions only necessary if fines not paid
- After one period of punishment actions, remaining punishment can be settled again with a fine
- \Rightarrow Optimal penal codes can be described by one action profile per state (plus transfer / fine scheme)

• For mixed action profiles transfer make a player indifferent between all pure actions in the support

Optimal Simple Equilibria & Algorithms

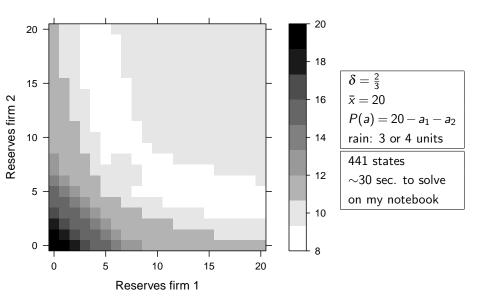
 Paper develops additional results for finding optimal simple equilibria that can implement every SPE payoff by varying upfront transfers.

- different numerical algorithms
- guidance to find closed-form solutions

Solving the model of Cournot Competition with Stochastic Reserves...

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Prices under Collusion



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• State describes whether principal has a durable product: $x \in \{0,1\}$

$$\pi_P(a,x)=x$$

• Agent can exert costly effort to build or destroy the product $a \in \{-1, 0, 1\}$

$$\pi_{\mathcal{A}}(a,x) = -c|a|$$

 $x' = \min\{\max\{x+a,0\},1\}$

• Unique MPE: no transfers, a(x) = 0

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'grim-trigger-style" equilibria: after deviation play MPE forever

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• Unique MPE: no transfers, a(x) = 0

'grim-trigger-style" equilibria: after deviation play MPE forever \Rightarrow only zero effort can be implemented

• State describes whether principal has a durable product: $x \in \{0,1\}$

$$\pi_P(a,x)=x$$

• Agent can exert costly effort to construction or destroy the product $a \in \{-1, 0, 1\}$

$$x'=\min\{\max\{x+a,0\},1\}$$
 $\pi_{\mathcal{A}}(a,x)=-c|a|$

• Unique MPE: a(x) = 0, no transfers

Optimal simple equilibria: construction in equilibrium phase and destruction as punishment whenever

$$(1-\delta^2)c\leq \delta^2.$$

Summary

- Allow transfers & assume risk-neutrality in discounted stochastic game
 - Every SPE payoff can be implemented with simple equilibria

- Algorithms to solve for equilibrium payoff sets
- Results extend to imperfect monitoring of actions

Useful results to find optimal simple equilibria

- Perfect monitoring, finite action space, set of pure strategy SPE
- There are optimal transfers for given actions $(a^k(x))_{\forall k,x}$

Computing joint equilibrium payoffs and punishment payoffs

$$U(x|a^{e}) = (1-\delta)\Pi(a^{e}(x), x) + \delta E[U(x'|a^{e})|a^{e}(x), x]$$

$$v_{i}(x|a^{i}) = \max_{a_{i} \in A(x)} \{(1-\delta)\pi_{i}(a, x) + \delta E[v_{i}(x'|a^{i})|a_{i}, a^{i}_{-i}(x), x]\}$$

 $a^{k}(x)$ can be implemented if and only if

$$(1-\delta)\Pi(a^{k}(x),x) + \delta E[U(x'|a^{e})|a^{k}(x),x] \geq \sum_{i=1}^{n} \max_{a_{i} \in A(x)} \{(1-\delta)\pi_{i}(a_{i},a_{-i}^{k}(x),x) + \delta E[v_{i}(x'|a^{i})|a_{i},a_{-i}^{k}(x),x]\}$$

Basic idea of one algorithm

- Assume in round r all action profiles in A^r(x) ⊂ A(x) can be implemented
- In round r = 0 all action profiles can be implemented

Let

$$U(x|A^{r}) = \max_{a^{e} \in A^{r}} U(x|a^{e}) \text{ Markov decision process}$$
$$v_{i}(x|A^{r}) = \min_{a^{i} \in A^{r}} v_{i}(x|a^{i}) \text{ Nested Markov decision process}$$

- Let A^{r+1}(x) be all profiles that survive joint incentive constraints given U(.|A^r) and v_i(x|A^r)
- Stop once $A^r = A^{r+1}$

Public Correlation and Non-Optimality of Stationary Equilibrium paths

• Stage game:

	А	В
Α	0,0	-1,3
В	3,-1	0,0

- Mix between (A,B) and $(B,A) \rightarrow \delta \geq \frac{1}{2}$
- Alternate $\{(A,B),(B,A),(A,B),...\} \rightarrow \delta \geq \frac{1}{3}$