EXERCISE 4: ANISOTROPY

GOALS

Today we will learn how to use advanced material models beyond linear isotropic elasticity. We will switch to wood as an example for anisotropic material behavior.

A. Anisotropic Material

Up until now, we always used isotropic materials, i. e. materials whose properties are the same for every orientation. In reality, though, most materials exhibit anisotropy to some extent. Wood, for instance, is a commonly used "organic fiber-reinforced composite," whose material properties parallel to the grain differ significantly from those in directions perpendicular to the fibers. Instead of a fully anisotropic material model (= 21 independent parameters, possible shear coupling) wood is often modeled as either an orthotropic (= 9 independent parameters, three orthogonal planes of symmetry) or transverse isotropic material (= 5 independent parameters, two elasticity moduli, rotational symmetry).

We will use an orthotropic material model to describe the mechanical behavior of a solid body made of a piece of wood. First, we need to agree on a material coordinate system. For wood, it is common to consider the direction parallel to the grain the *x* (or longitudinal) direction; the direction normal to the growth rings is the *y* (or radial direction); and finally, *z* is the direction tangential to the growth rings (Figure 1).





FIGURE 1: MATERIAL COORDINATE SYSTEM FOR WOOD

Create a new **Static Structural** analysis system (or an entirely new project). Then add a new orthotropic material model (**Engineering Data** \rightarrow **Linear Elastic** \rightarrow **Orthotropic Elasticity**). Extract the 9 required material parameters from the following PDF file about the material properties of different wood types (pages 2 – 8)

 \rightarrow <u>http://www.woodweb.com/Resources/wood eng handbook/Ch04.pdf</u>,

You can choose any type of wood you'd like, e. g. pine. Just make sure that your material properties use the coordinate system of Figure 1.

Next, start **Design Modeler**. We will use a slightly more sophisticated geometry this time. Create the geometry using two box primitives to produce an L-shaped form, corresponding to Figure 2.



FIGURE 2: DIMENSIONS OF THE L-SHAPED GEOMETRY

Ensure that the result is a *single body*, not two bodies/two parts! When you are done with the geometry, start the **Mechanical** module.

By default, the coordinate system of each solid body – and hence its material – is the global coordinate system. Because we want to investigate the influence of different material alignment, we need to define a custom coordinate system: Right click on **Coordinate Systems** in the **Outline** and insert a new **Coordinate System** (and give it a distinct name).

To rotate or translate the coordinate system, select it from the outline and click on the corresponding buttons in the toolbar (Figure 3). This will add **Rotate X/Y/Z** or **Translate X/Y/Z** properties to the **Transformations** section of your coordinate system where you can enter the desired values (rotation angles).



FIGURE 3: ROTATING AND TRANSLATING A CUSTOM COORDINATE SYSTEM

Don't forget to assign both the wood material *and* the new coordinate system to the solid body (Geometry → Solid → Definition → Coordinate System)!

After creating an appropriate mesh, add load and boundary conditions as depicted by Figure 4. You may also want to switch on support for large deflections as we did in today's first exercise.



FIGURE 4: LOAD AND BCS APPLIED TO THE WOODEN STRUCTURE

Questions

- Why didn't we need to define v_{yx} , v_{zy} , v_{zx} ?
- Where do you see compression, where tension?
- Try out different fiber alignments (e. g. 45°, 90°, 135°, -45° ...). Which material orientation leads to the lowest amount of deformation? Why?





B. Bonus: Anisotropy & 2D Modeling

We want to optimize our wooden part a bit further and replace the single solid body by two independent, but "glued together" solid bodies. This way, each body can define its own unique fiber orientation (just as if it was made of two wooden blocks). Instead of a fully three-dimensional model however, we will use an analogous plane stress 2D model this time.

Create a new project and add a **Static Structural** analysis system. Define the wood material as before. Back in the **Project Schematic**, right click **Geometry** and select **Properties**. In the properties window, set the **Analysis Type** to **2D** (Figure 6).



FIGURE 6: CHANGING THE ANALYSIS TYPE TO 2D

Now, launch **DesignModeler** and add a sketch to the **XYPlane** (see D.1 of lab 2 for details). Sketch the edges of the horizontal part of the L-shape (Figure 7). You may again consult the previous lab for details on how to add dimensions (lengths, angles) etc.

When you are done sketching, insert a surface body (**Concept** → **Surfaces from Sketches**). Select **Sketch1** as the Base Object and set **Operation** to **Frozen**. Next, we want to create the vertical part of the L-shape. After the **SurfaceSk1** item, insert a **Body Operation** (**Create** → **Body Operation**). Set **Preserve Bodies?** to **Yes** (we want to make a copy), set its type to **Rotate**, its **Z Component** to 1 and the **Angle** to 90°. After this body operation, insert a **Surface Flip** (**Tools** → **Surface Flip**) and after that another body operation. In this case, set **Preserve Bodies?** to **No**, set the **Y Component** to 1 and the **Angle** to 180°. Clicking the Generate button should create two parts and two bodies. Group both bodies into a single part (Figure 8).



FIGURE 7: SKETCHING THE 2D GEOMETRY

You can close the **DesignModeler** and launch the **Mechanical** module. Assign a unique custom coordinate system to each of the two bodies (horizontal and vertical part of the L-shape). Also make sure that the **Thickness** property of each body is set to 60 mm. Create a mesh and apply load and boundary conditions analogous to those of the 3D model.

Questions

- How do you need to align the wood of the two parts to minimize the deflection? Why?
- What is the deflection for the opposite configuration, i. e. when swapping the orientations of the two parts?



FIGURE 8: GROUPING BOTH SOLID BODIES INTO A SINGLE PART